

# SMART: Screen-based Gesture Recognition on Commodity Mobile Devices

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Fan Wu<sup>1</sup>, Qian Zhang<sup>4</sup>, Yi Wang<sup>2,5</sup>

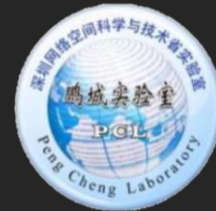
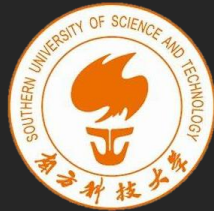
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Hong Kong University of Science and Technology<sup>4</sup>

Peng Cheng Laboratory<sup>5</sup>



MobiCom 2021

# In-air gesture control is natural and contactless



# Gesture control via hardware on mobile devices



Image

[CVPR'13,UIST'14]



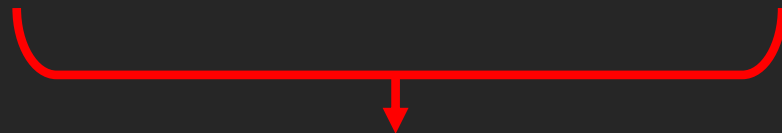
Acoustic

[CHI'12,MobiCom'16]



Wi-Fi

[Mobicom'15,Ubicomp'16]



*Privacy concerns*



*Background noise*

# Gesture control via hardware modification



Huawei  
Mate40

depth camera



Google  
Pixel 4

mmWave radar

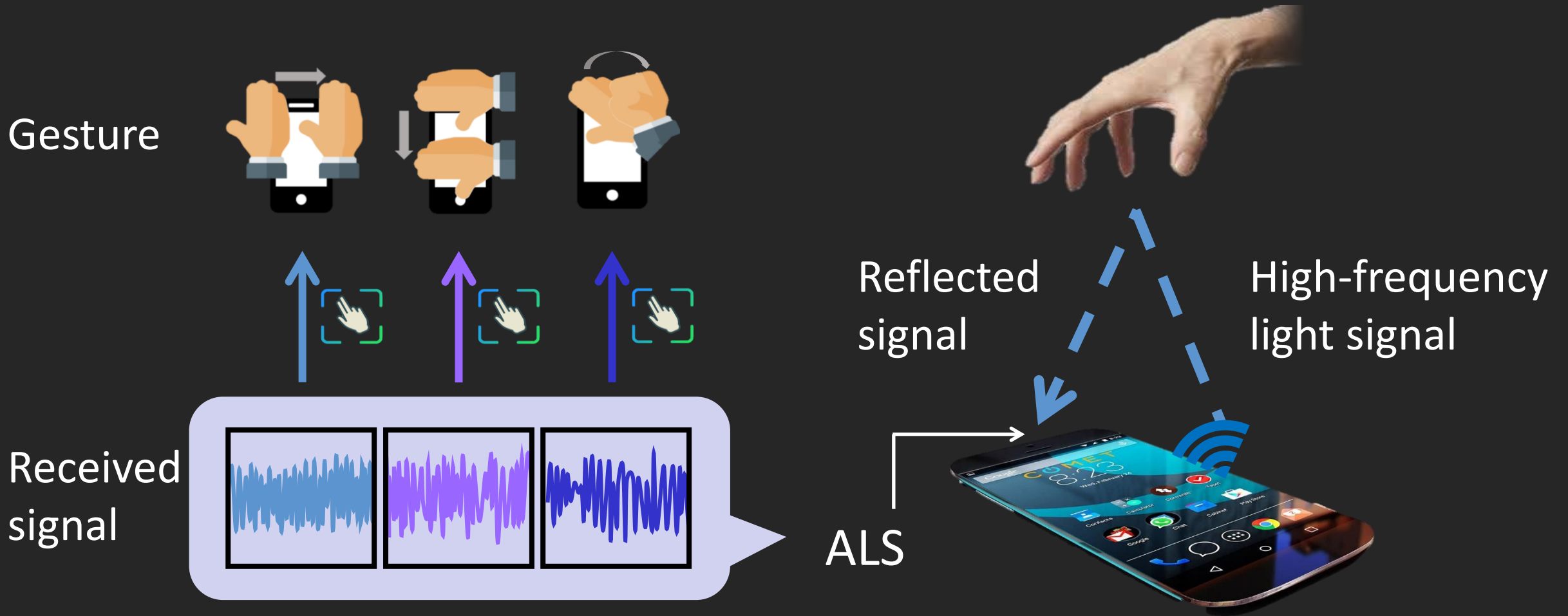


*Can we support in-air gesture recognition on legacy devices **without hardware modification?***

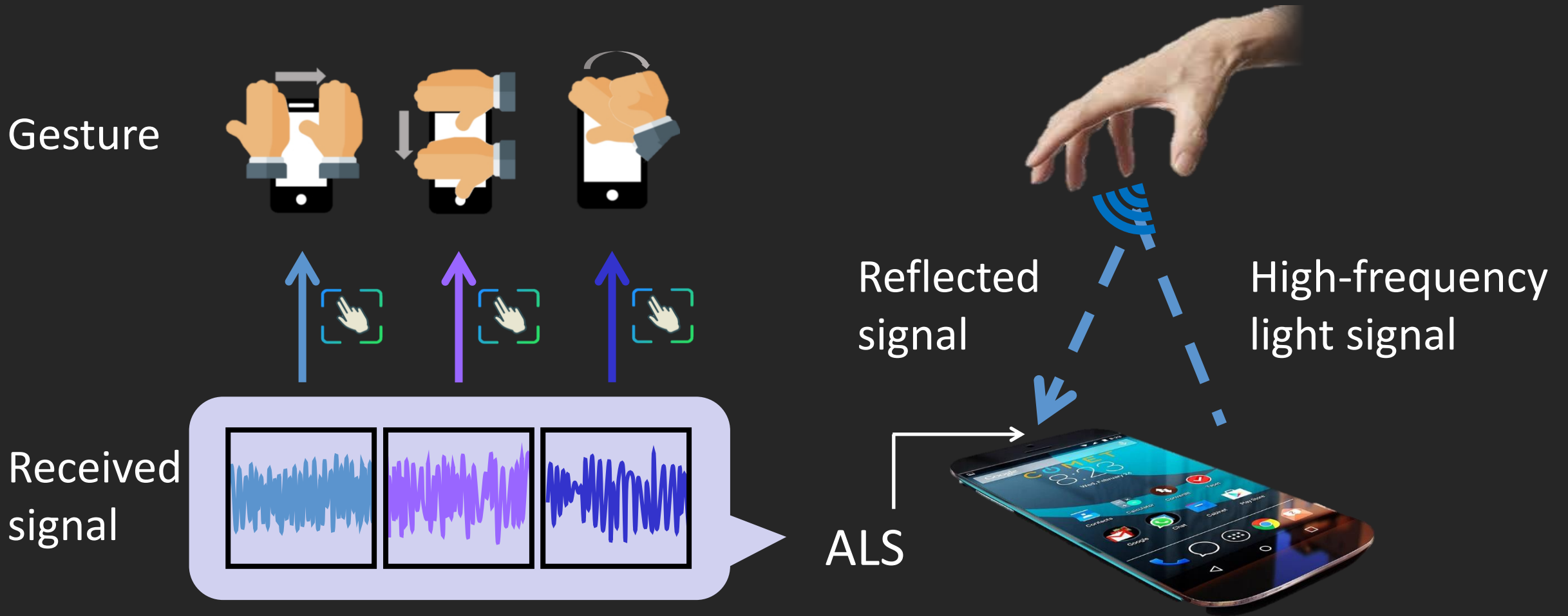
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SMART: A gesture recognition system leveraging **the screen and ambient light sensor(ALS)**.

# SMART: A gesture recognition system leveraging the screen and ambient light sensor(ALS).

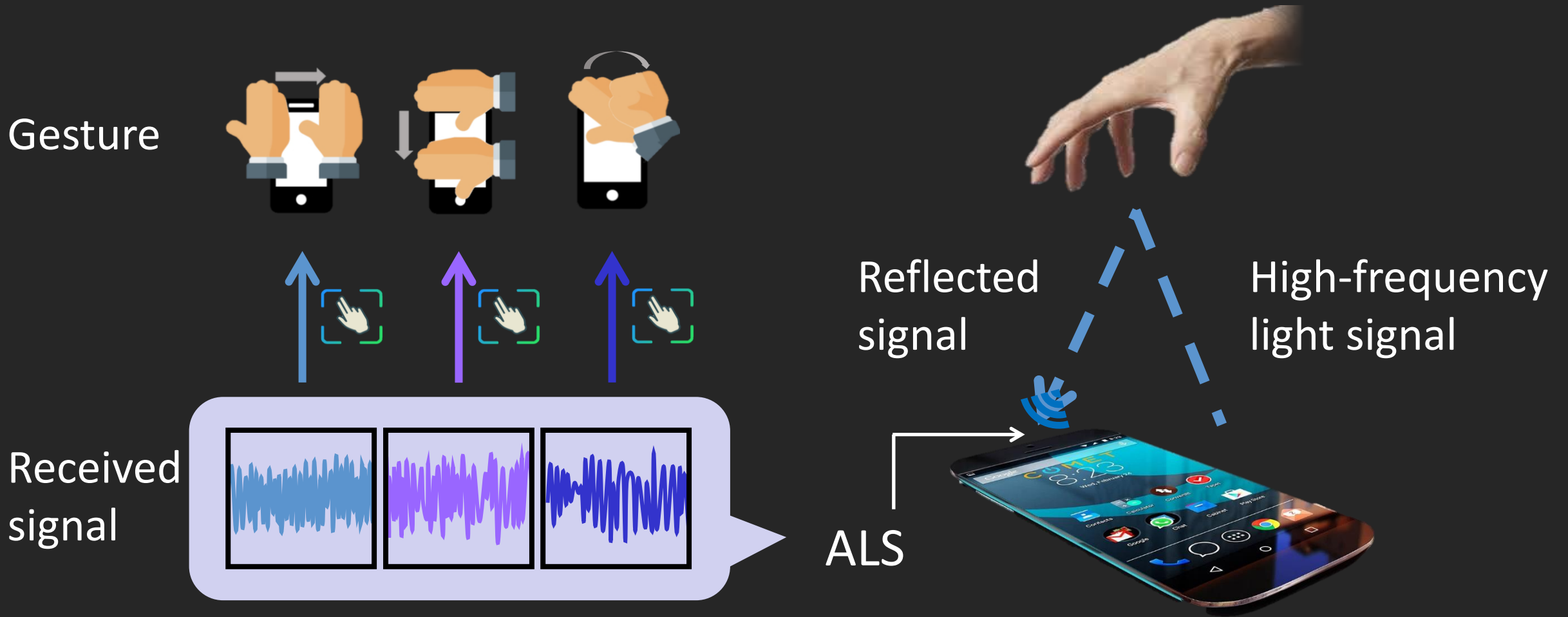


# SMART: A gesture recognition system leveraging the screen and ambient light sensor(ALS).



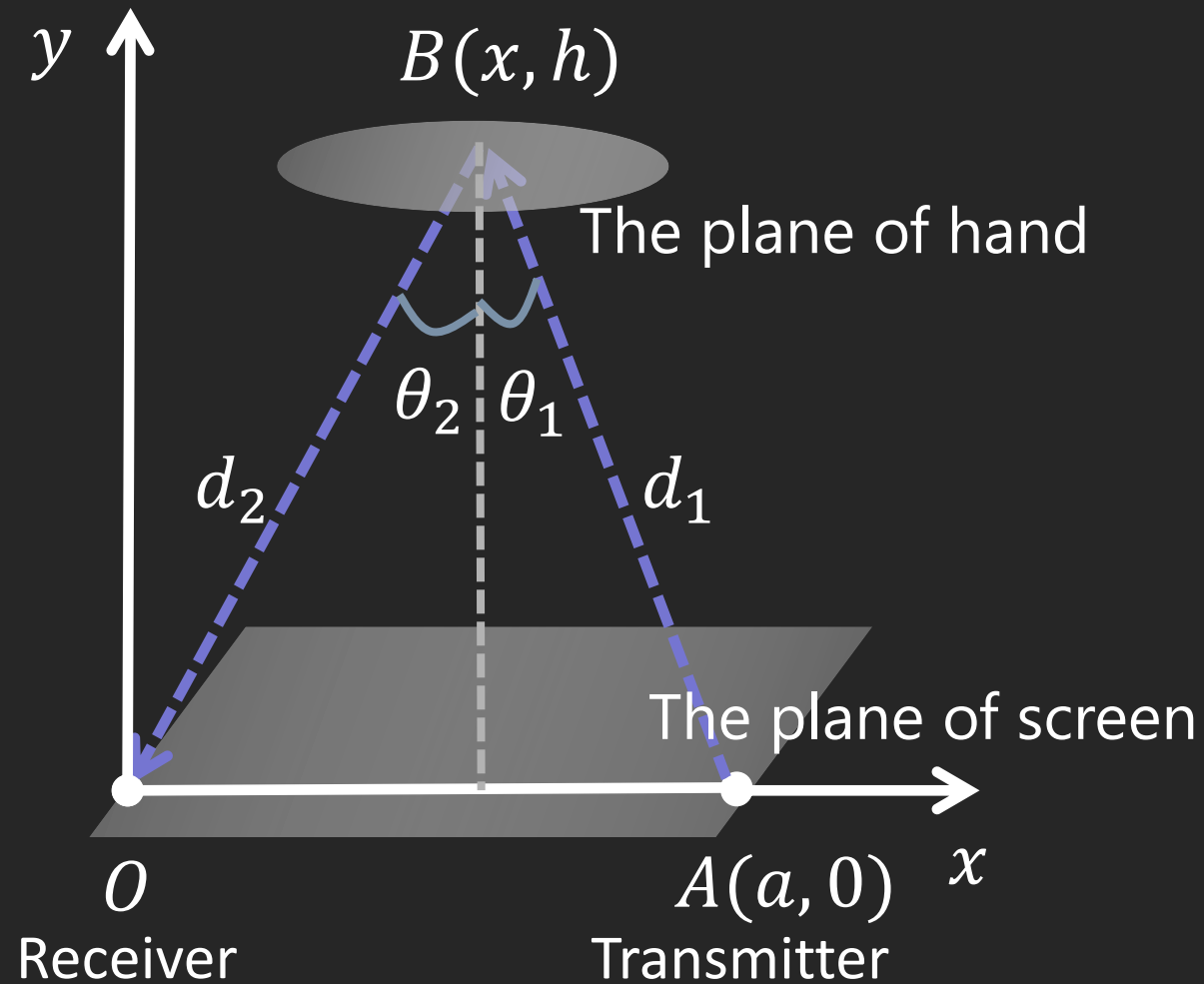


# SMART: A gesture recognition system leveraging the screen and ambient light sensor(ALS).



What is the relationship between the received light power and the hand gesture?

# Model the “Screen-Hand-ALS” channel



# Calculate received power

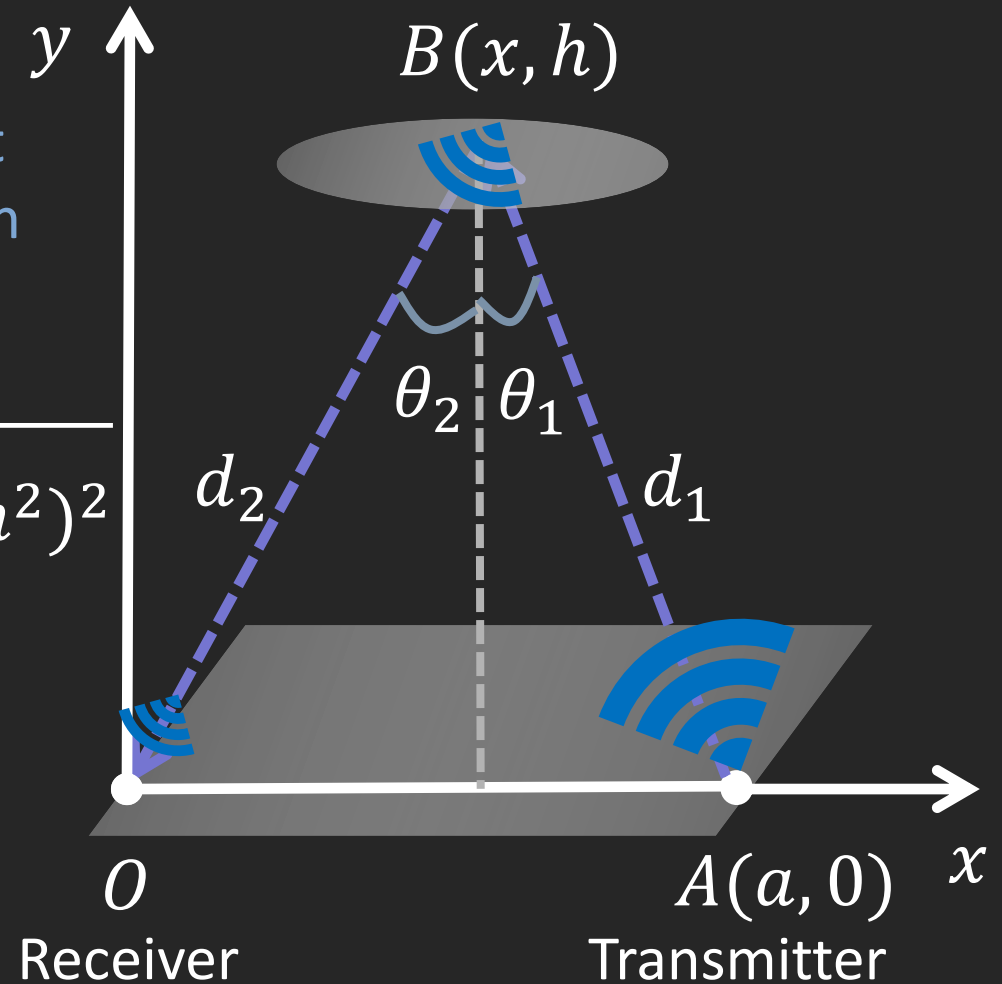
$$\begin{aligned}
 I_O &= I_A \cdot l_{AB} \cdot l_B \cdot l_{BO} \cdot l_O \quad \text{Lambert radiation} \\
 &= I_A \cdot c \cdot \frac{\cos \theta_1}{d_1^2} \cdot \frac{\cos \theta_2}{d_2^2} \\
 &= I_A \cdot c \cdot \frac{h^3}{((x-a)^2 + h^2)^{\frac{3}{2}} (x^2 + h^2)^2}
 \end{aligned}$$

$I_O$ : signal power received by point O.

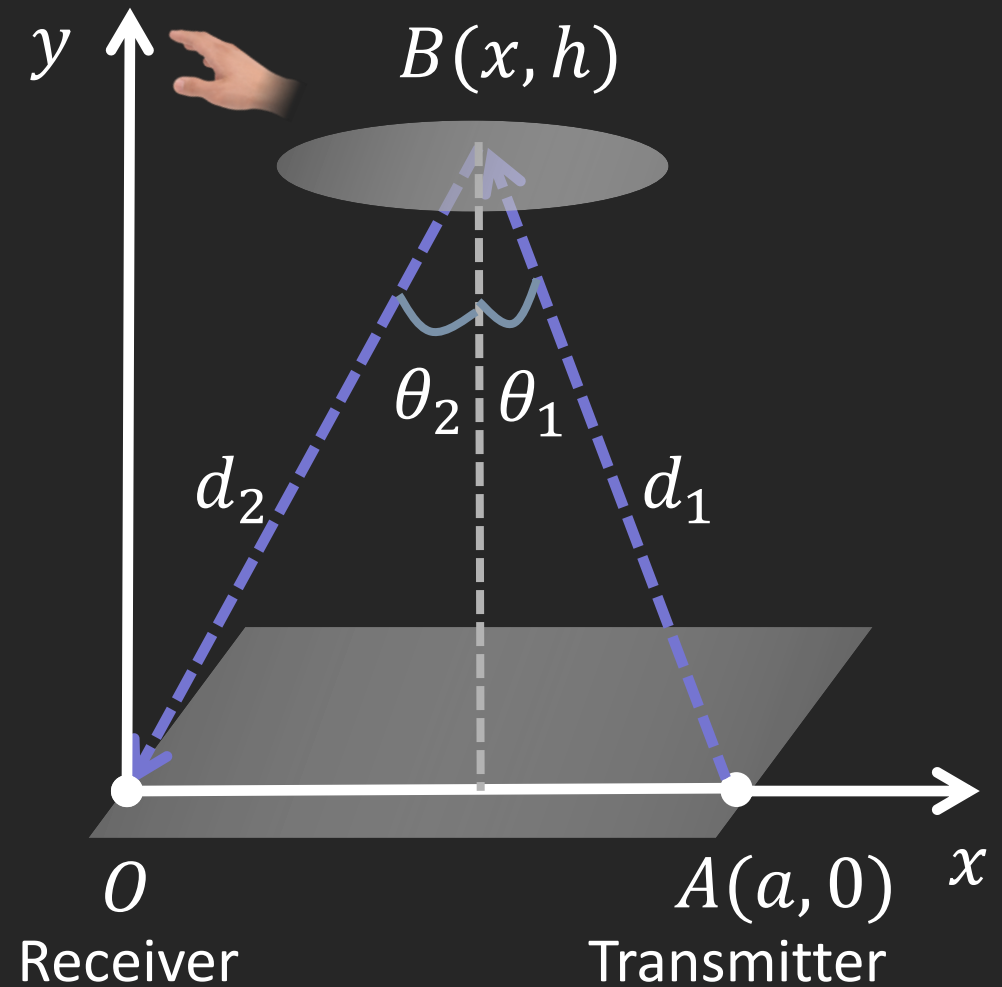
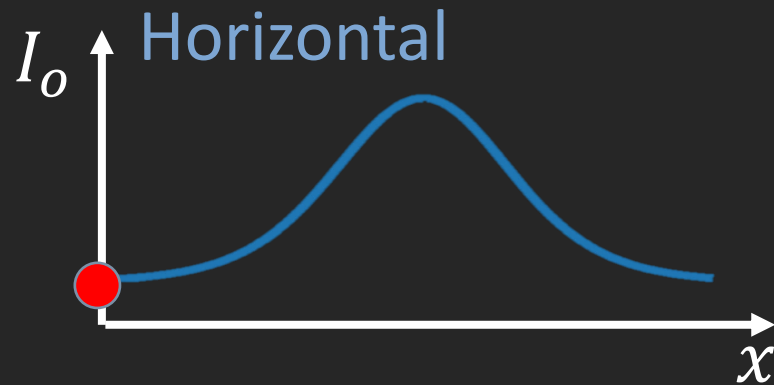
$I_A$ : signal power transmitted by point A.

$l_{AB}$ : loss from A to B.       $l_{BO}$ : loss from B to O.

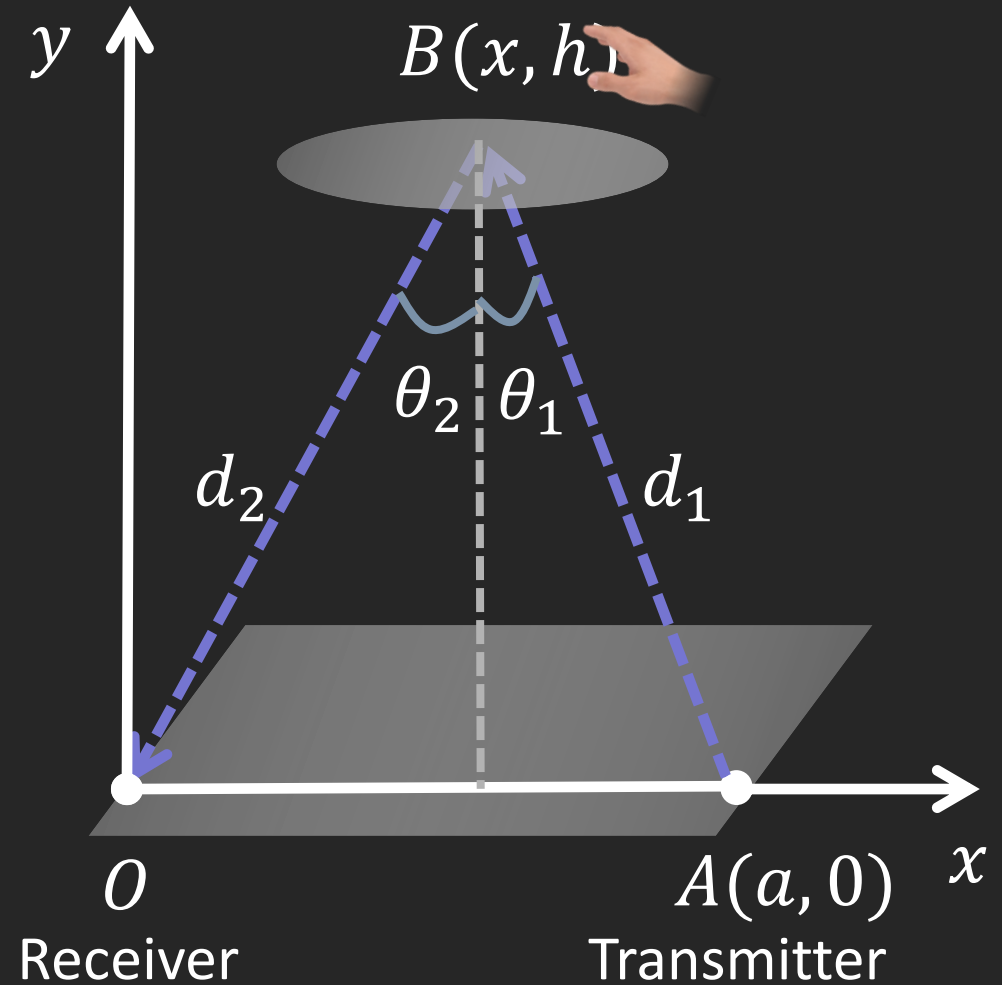
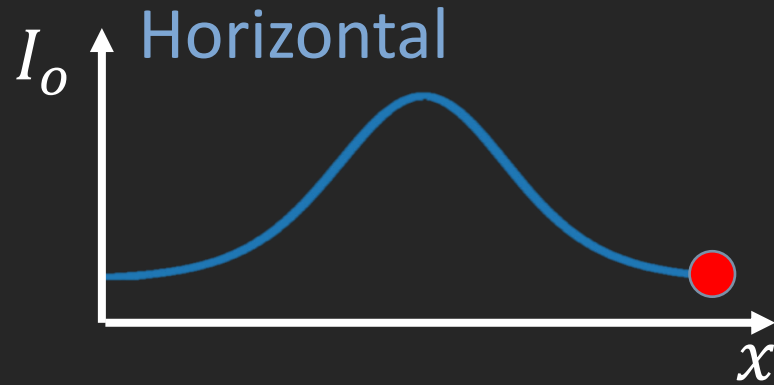
$l_B$ : loss at point B.       $l_O$ : loss at point O.



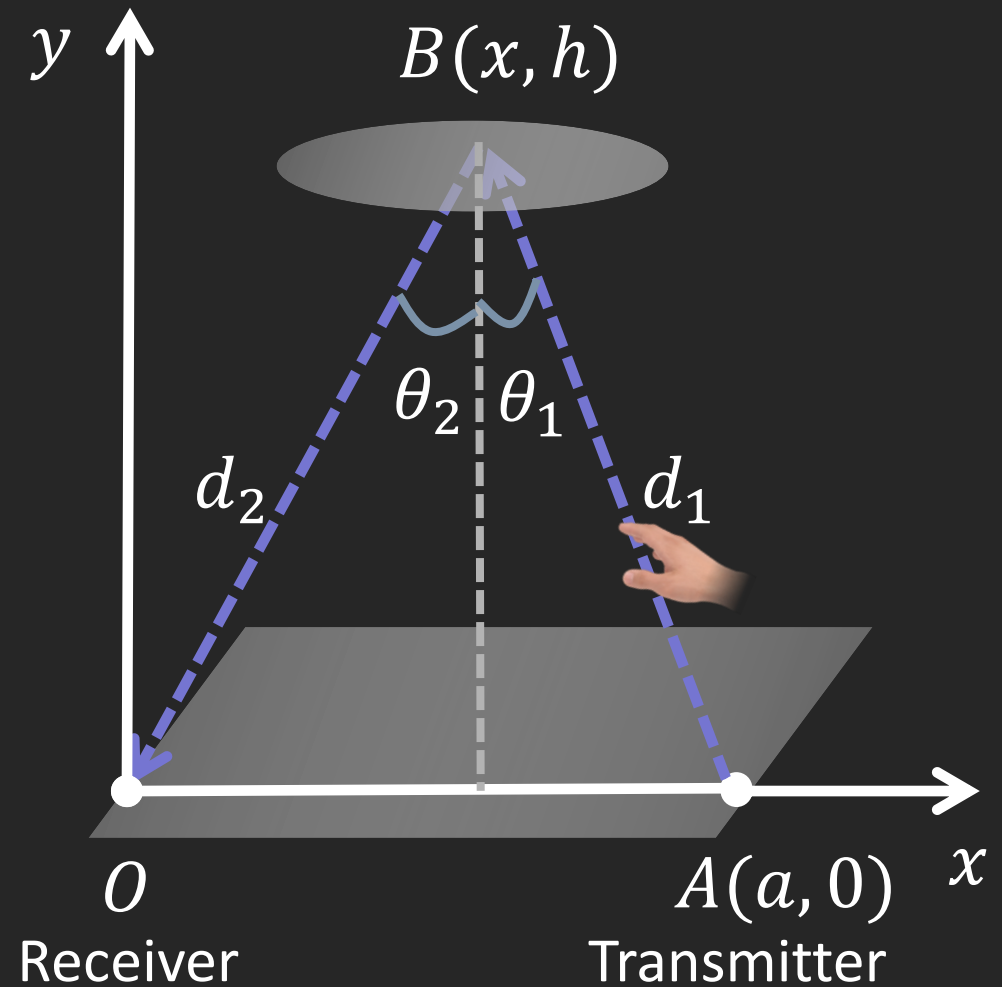
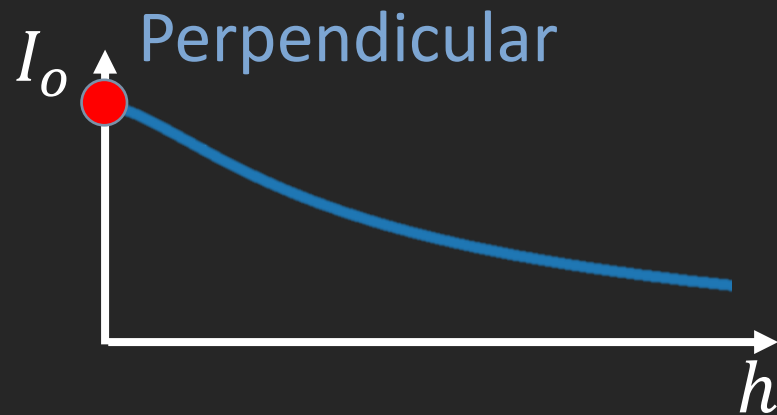
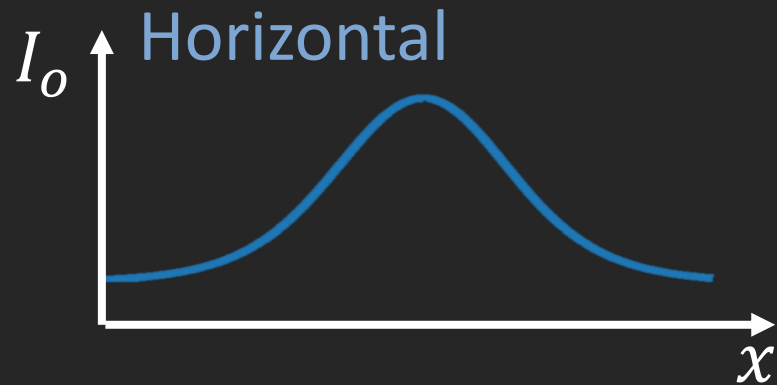
# Hand movement and received power



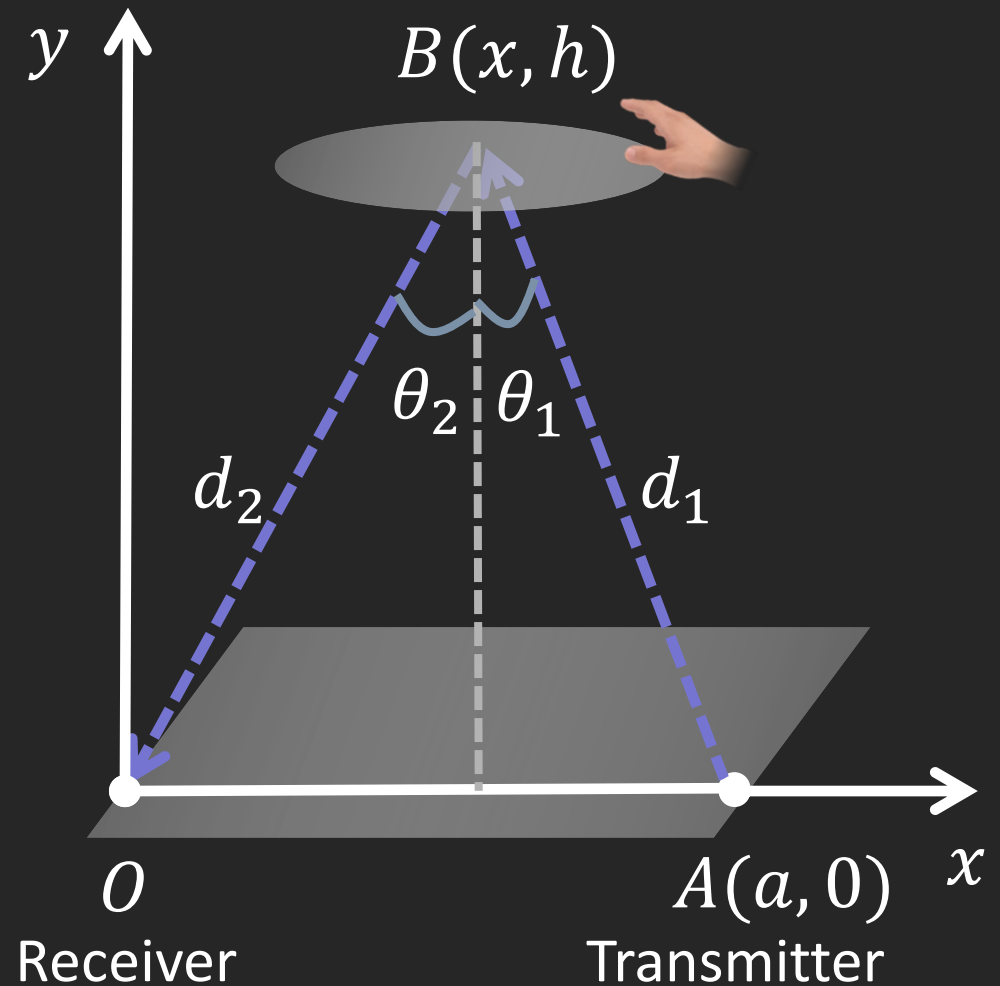
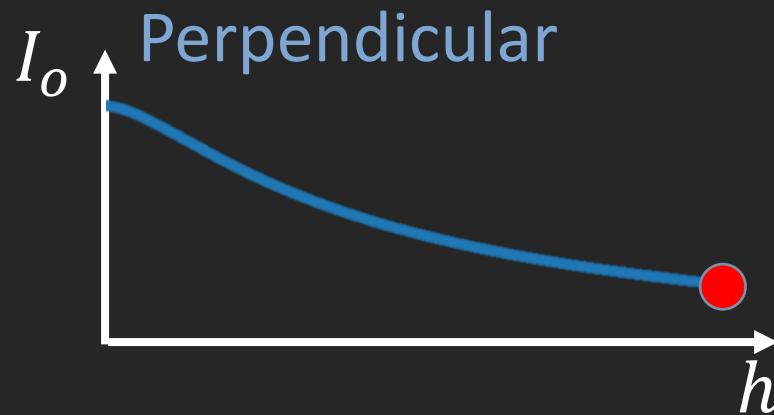
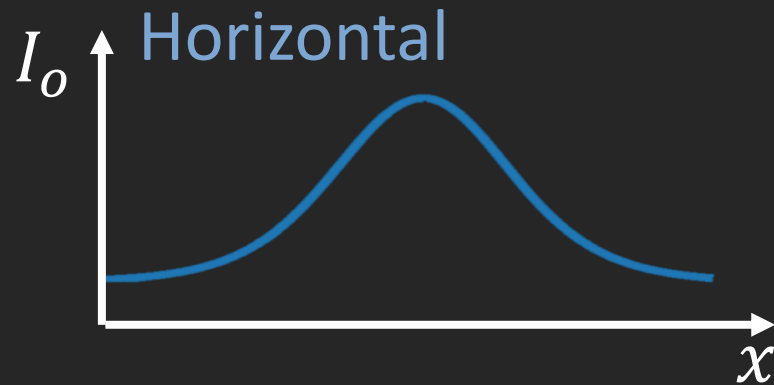
# Hand movement and received power



# Hand movement and received power



# Hand movement and received power



The fundamental working principle of SMART



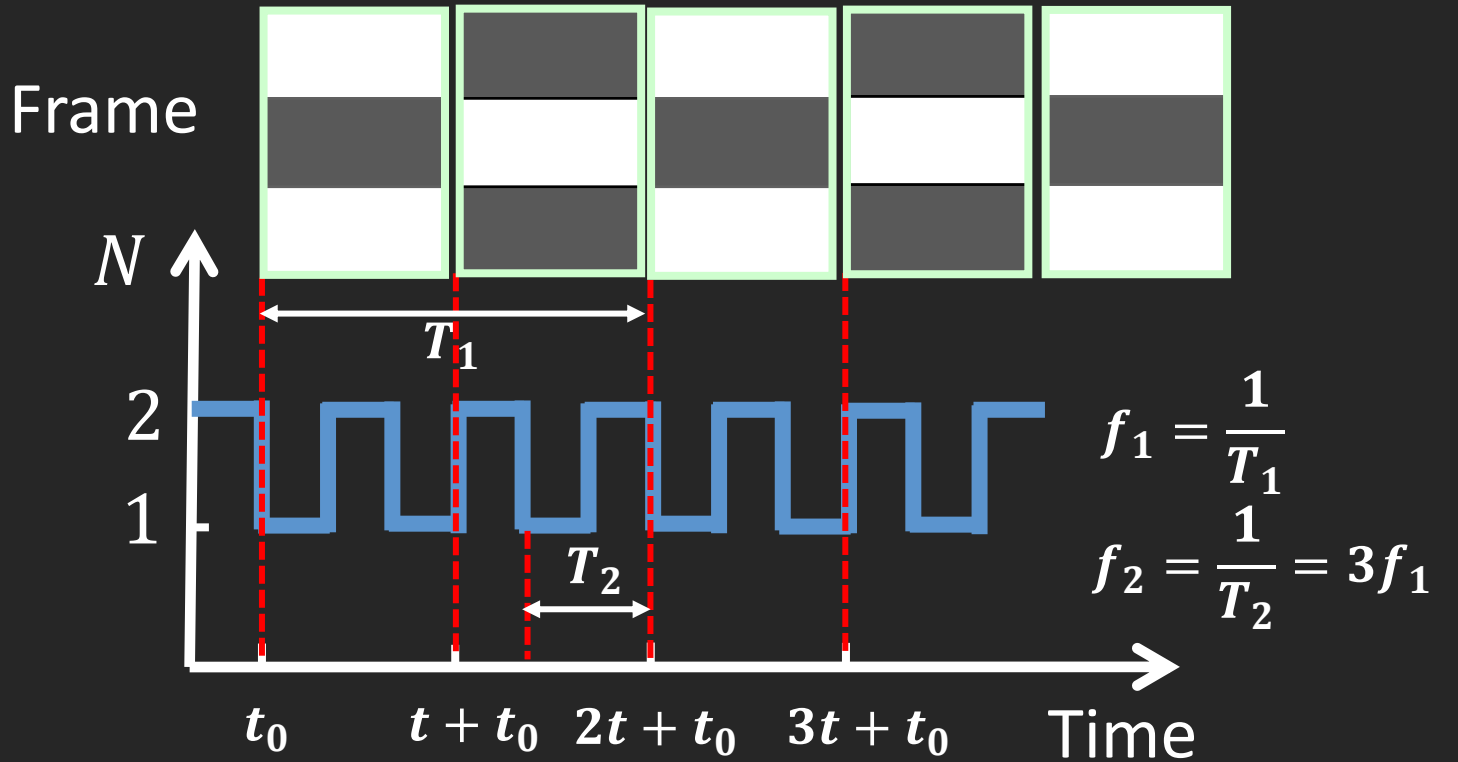
# Screen's refresh rate limits modulated frequency

Refresh time per frame	$t (= \frac{1}{f_r})$	$2t$	$3t$	... ..	$nt$
Frequency	$f_1$	$\frac{f_1}{2}$	$\frac{f_1}{3}$	... ..	$\frac{f_1}{n}$

  
**Lower frequency**

Higher frequency light signals are needed since human eyes are sensitive to low frequency flickering

# Transmit high frequency signal



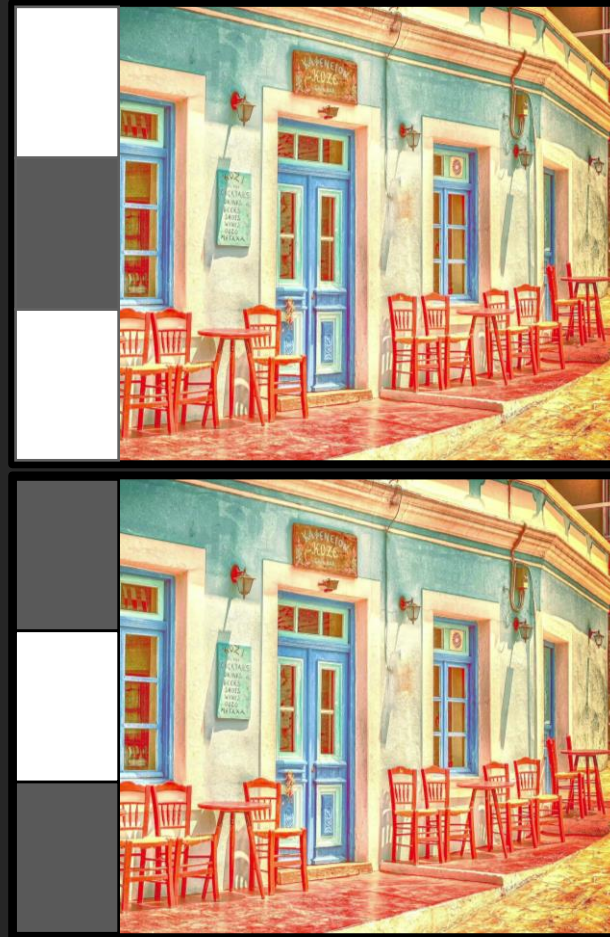
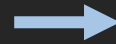
$N$ : the number of bright blocks

$t$ : refreshing time per frame

# Hide signals in the screen content



# Color decomposition of each pixel



Color space: RGB  $\rightarrow$  CIE 1931

$$\max \Delta Y = |Y_1 - Y_2|$$

$$s. t. \quad x_1 = x_2 = x_0,$$

$$y_1 = y_2 = y_0,$$

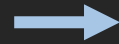
$$Y_0 = \frac{Y_1 + Y_2}{2}$$

Maximum luminance change.

The same chromaticity.

Color additive rule.

# Color decomposition of each pixel



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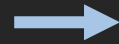
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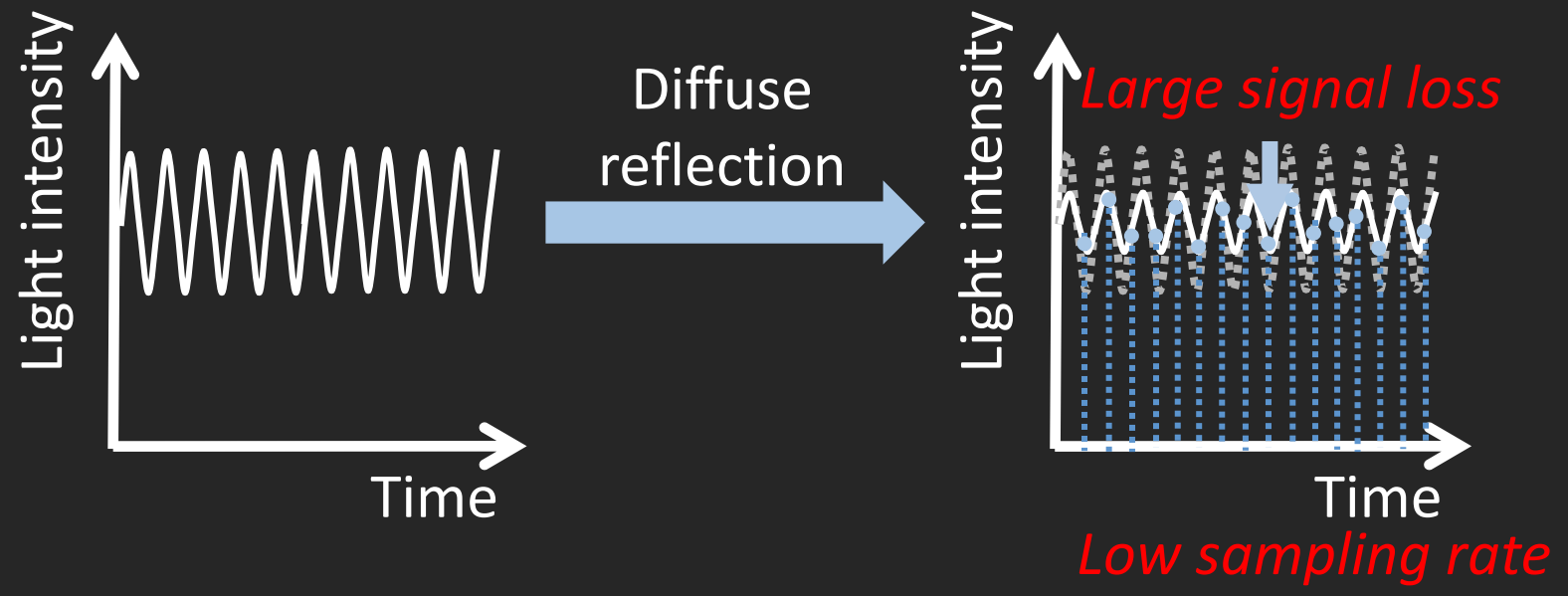
# Edge smoothing



Relieve phantom array effect



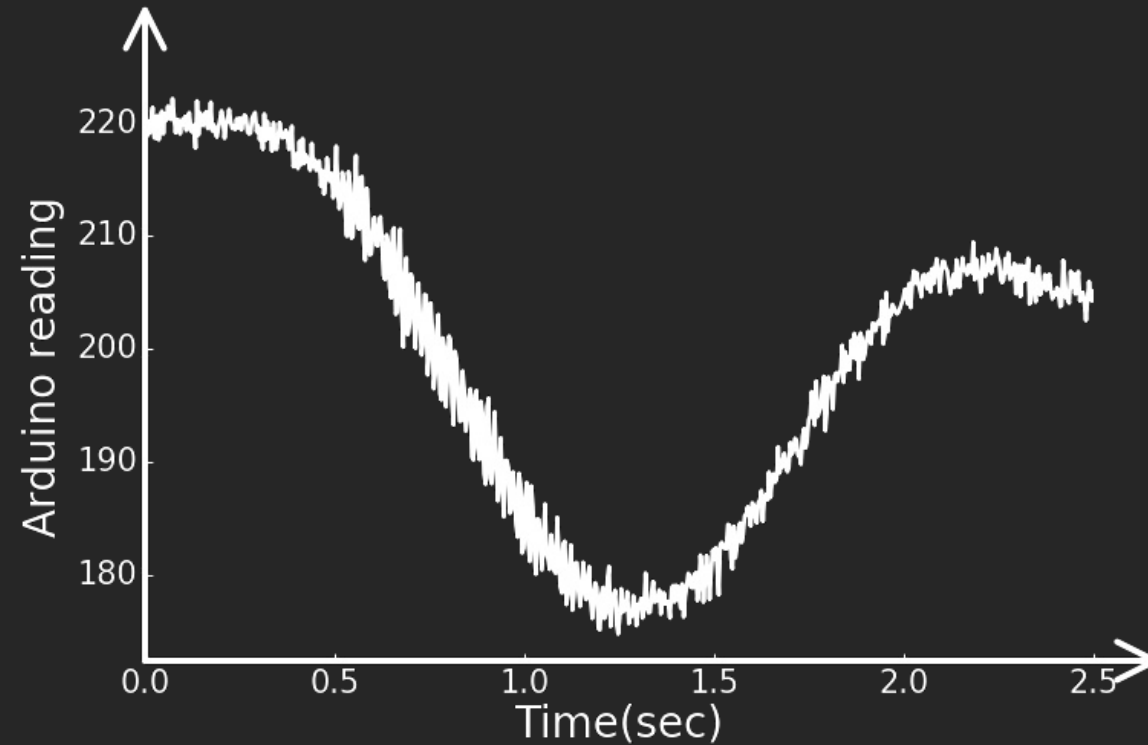
# Signal received by ALS is low-quality





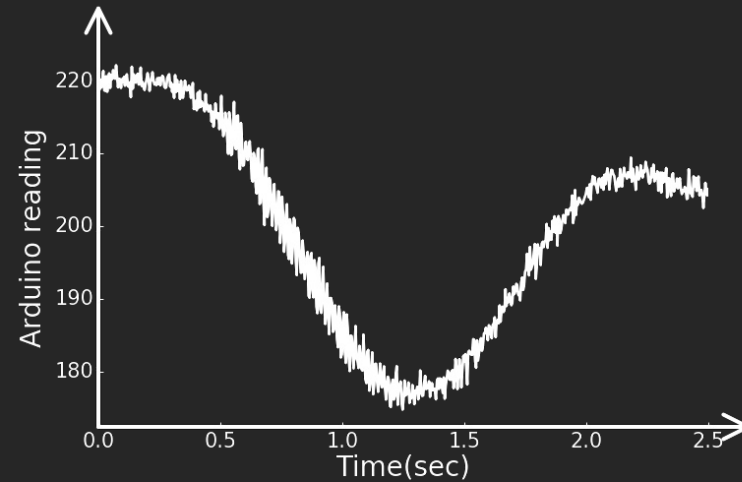
# Segmentation according to reflected power

Raw signal

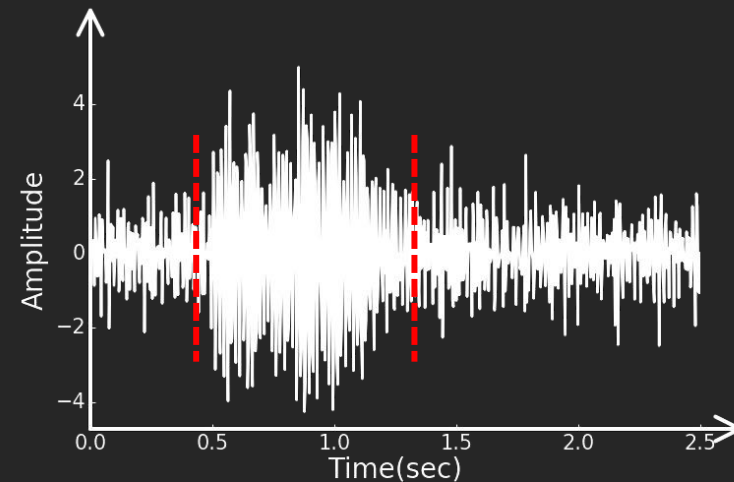


# Segmentation according to reflected power

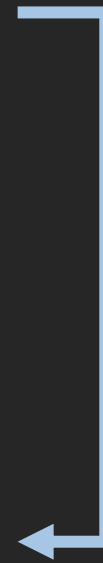
Raw signal



Reflected signal

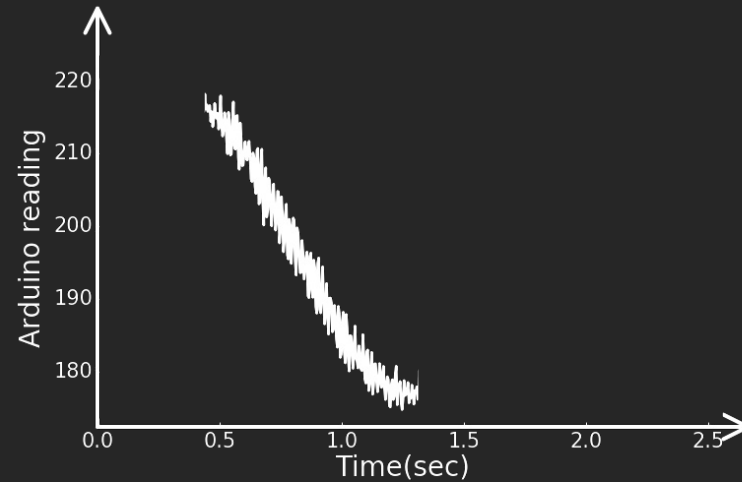


High-pass filter

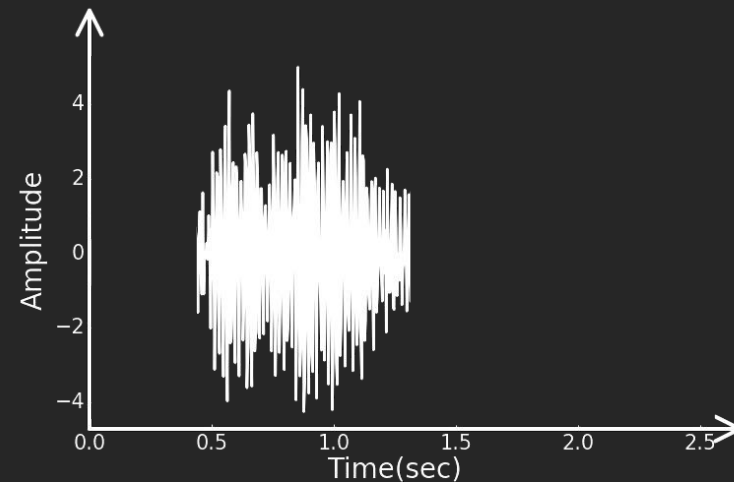


# Segmentation according to reflected power

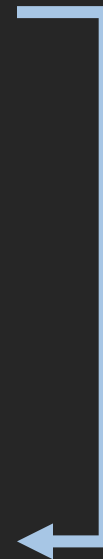
Raw signal



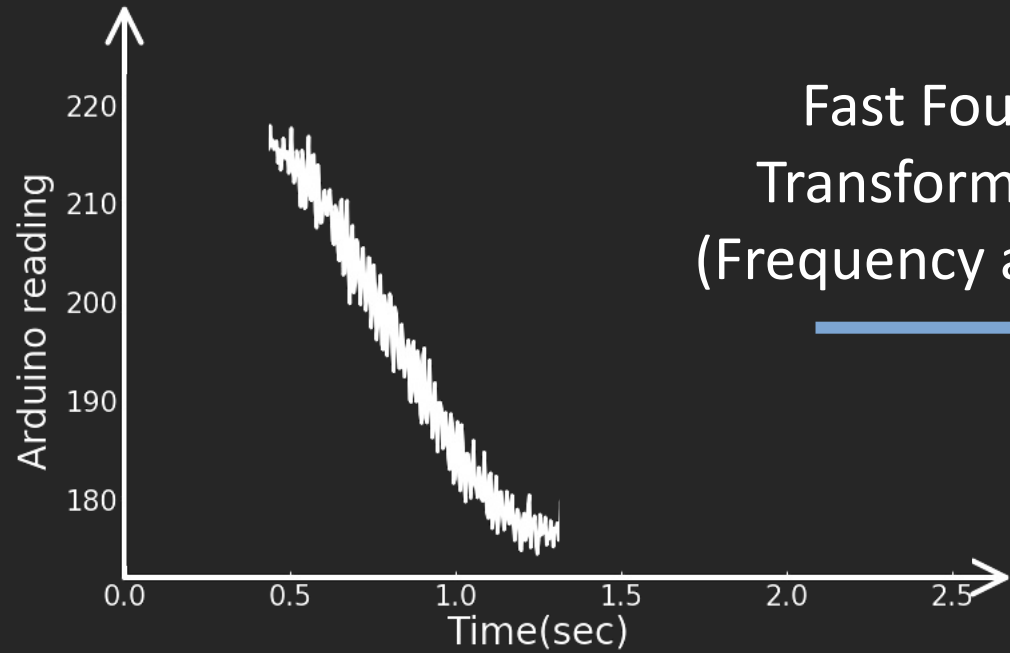
Reflected signal



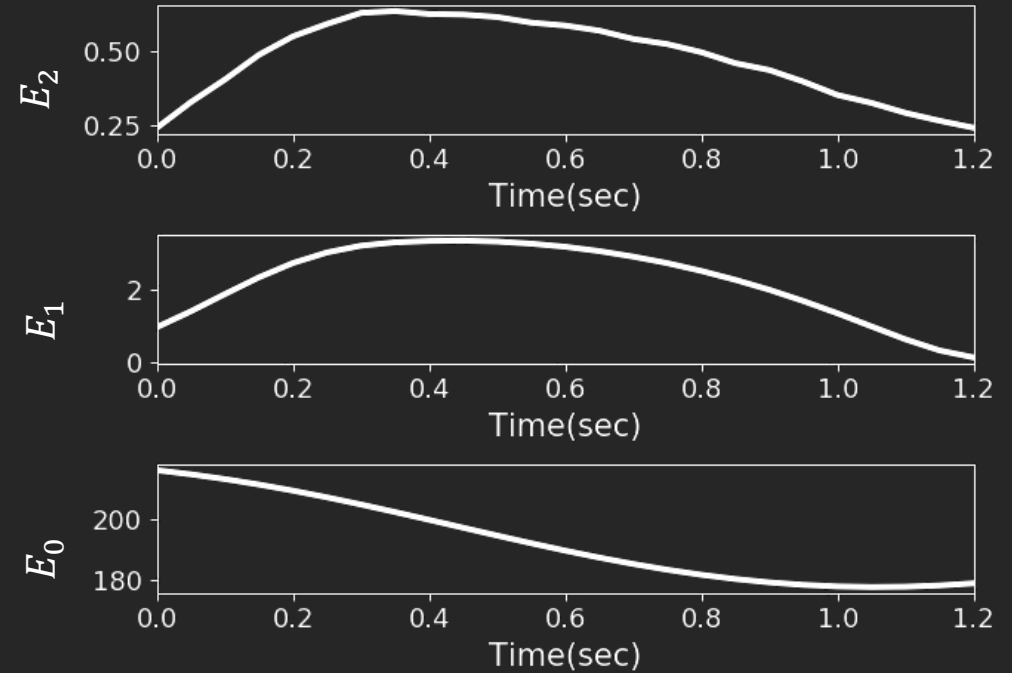
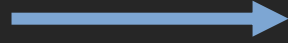
High-pass filter



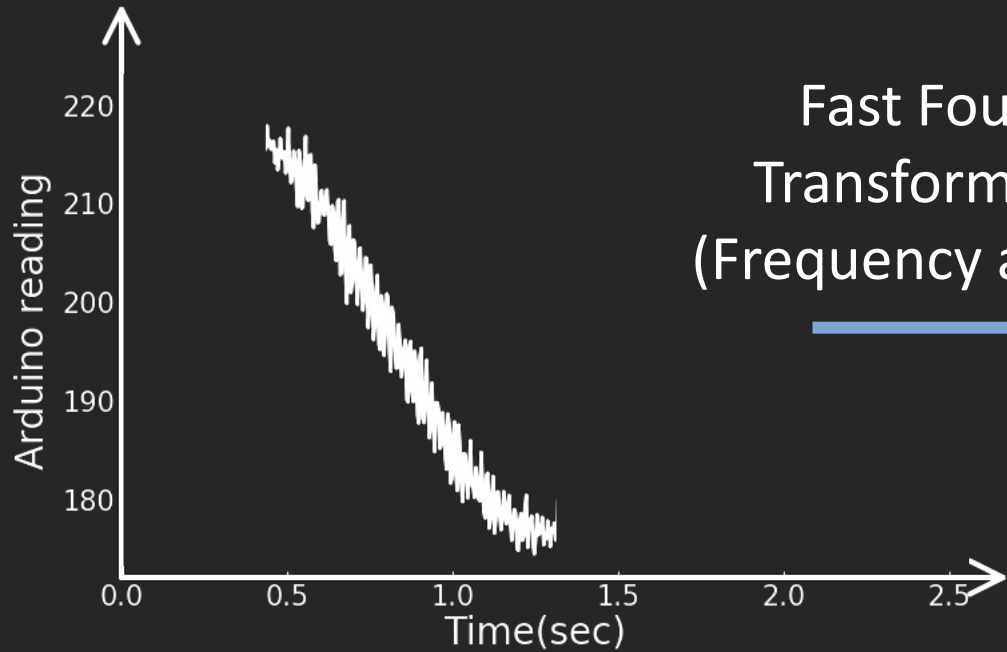
# Signal pre-processing and classification



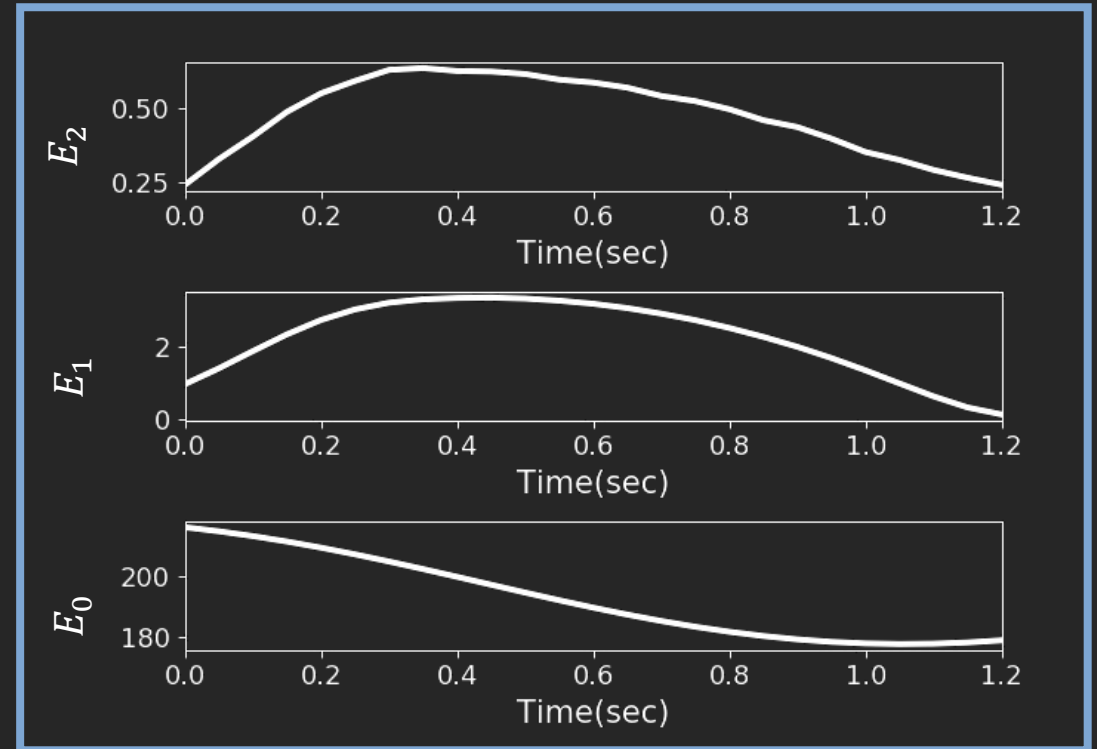
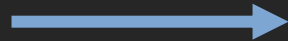
Fast Fourier  
Transformation  
(Frequency aliasing)



# Signal pre-processing and classification

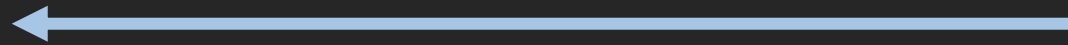


Fast Fourier  
Transformation  
(Frequency aliasing)



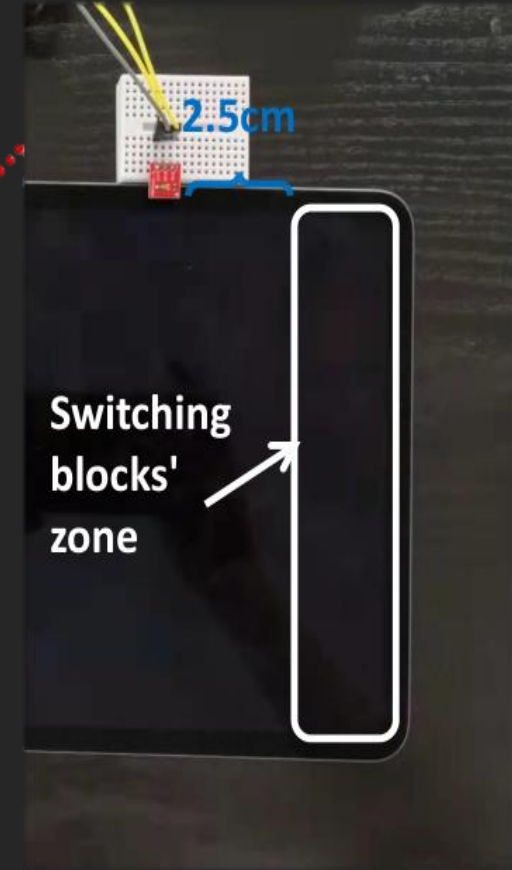
Feature extraction & Classification

Gesture recognition



# Evaluation

- Prototype
  - Transmitter: iPad Pro 11;
  - Receiver:  
TEMT6000(250Hz);  
Arduino Due;
- Experiment setting
  - 9 gestures;
  - 8 users;
  - 5 static & 2 dynamic lighting environments;



# Evaluation

- Prototype

- Transmitter: iPad Pro 11;
- Receiver: TEMT6000(250Hz); Arduino Due;

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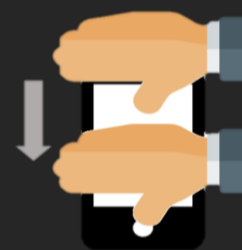
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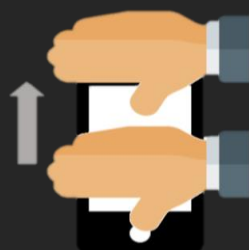
LeftRight



RightLeft



TopBottom



BottomTop



Fist



Openhand



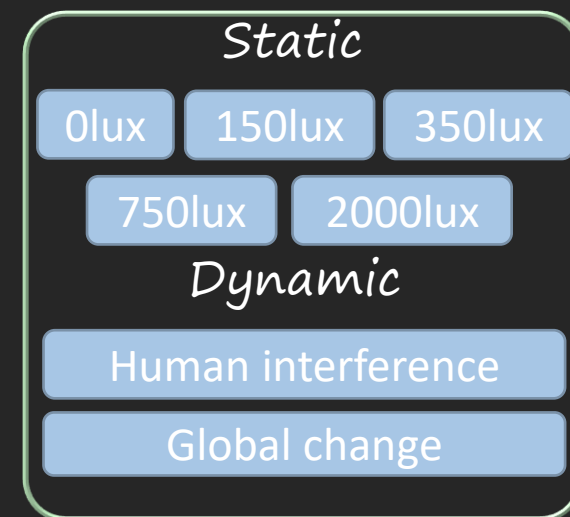
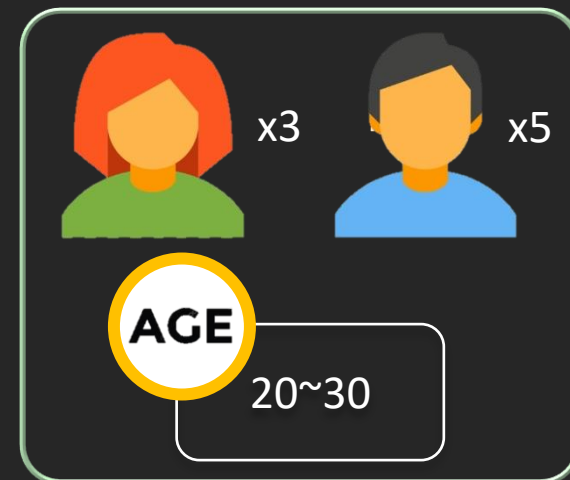
UpDown



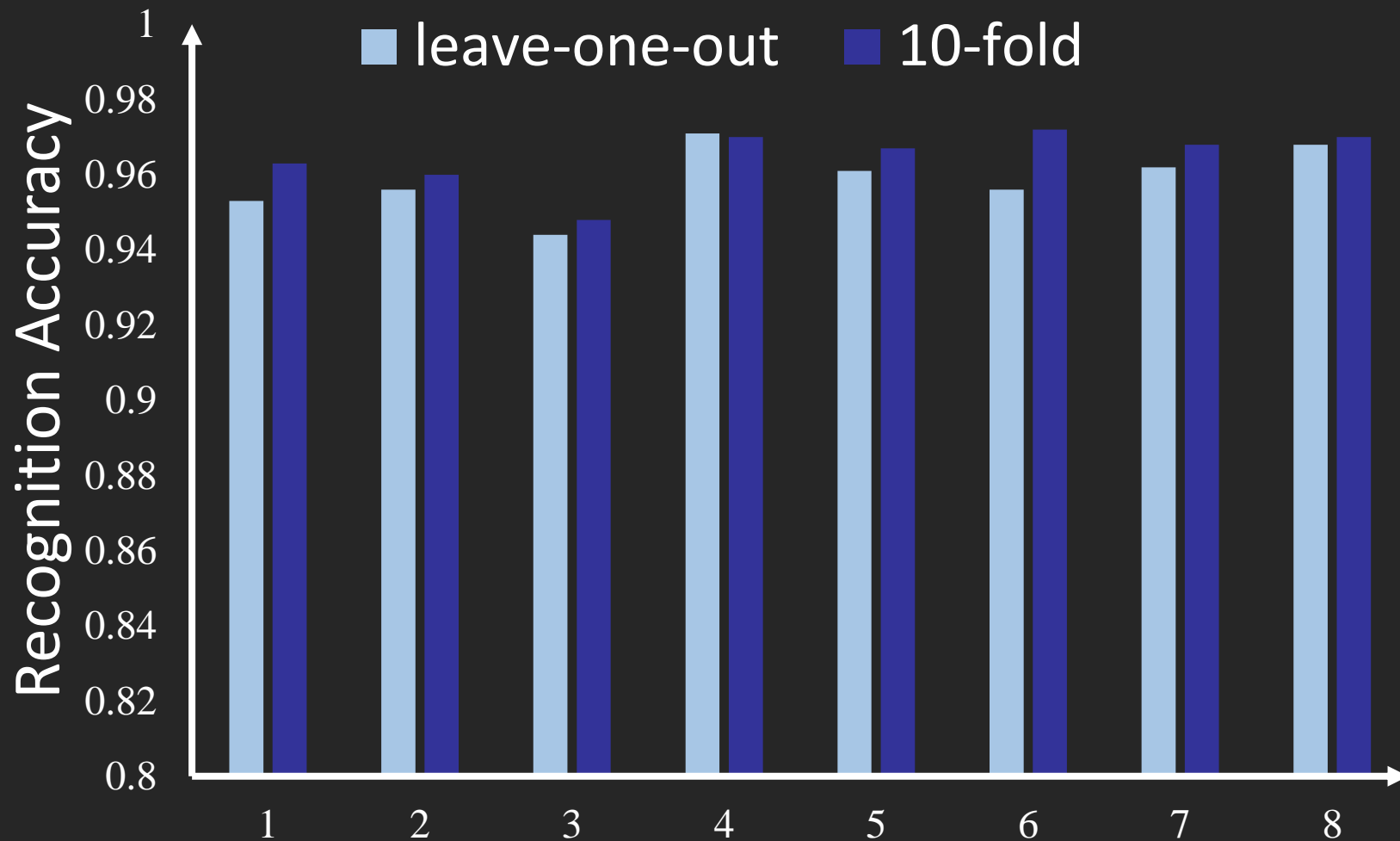
DownUp



Flip



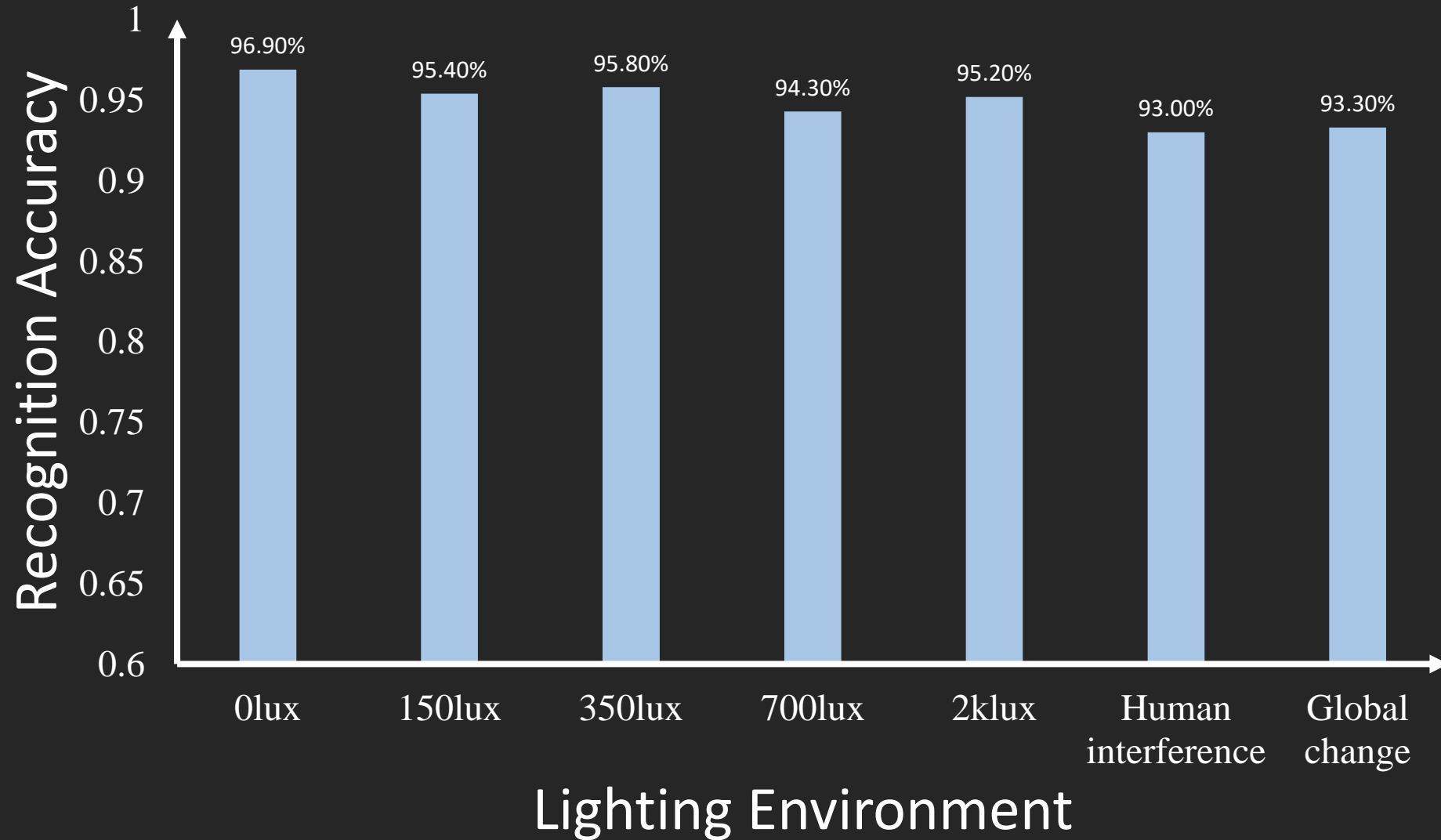
# Accuracy v.s. Different users



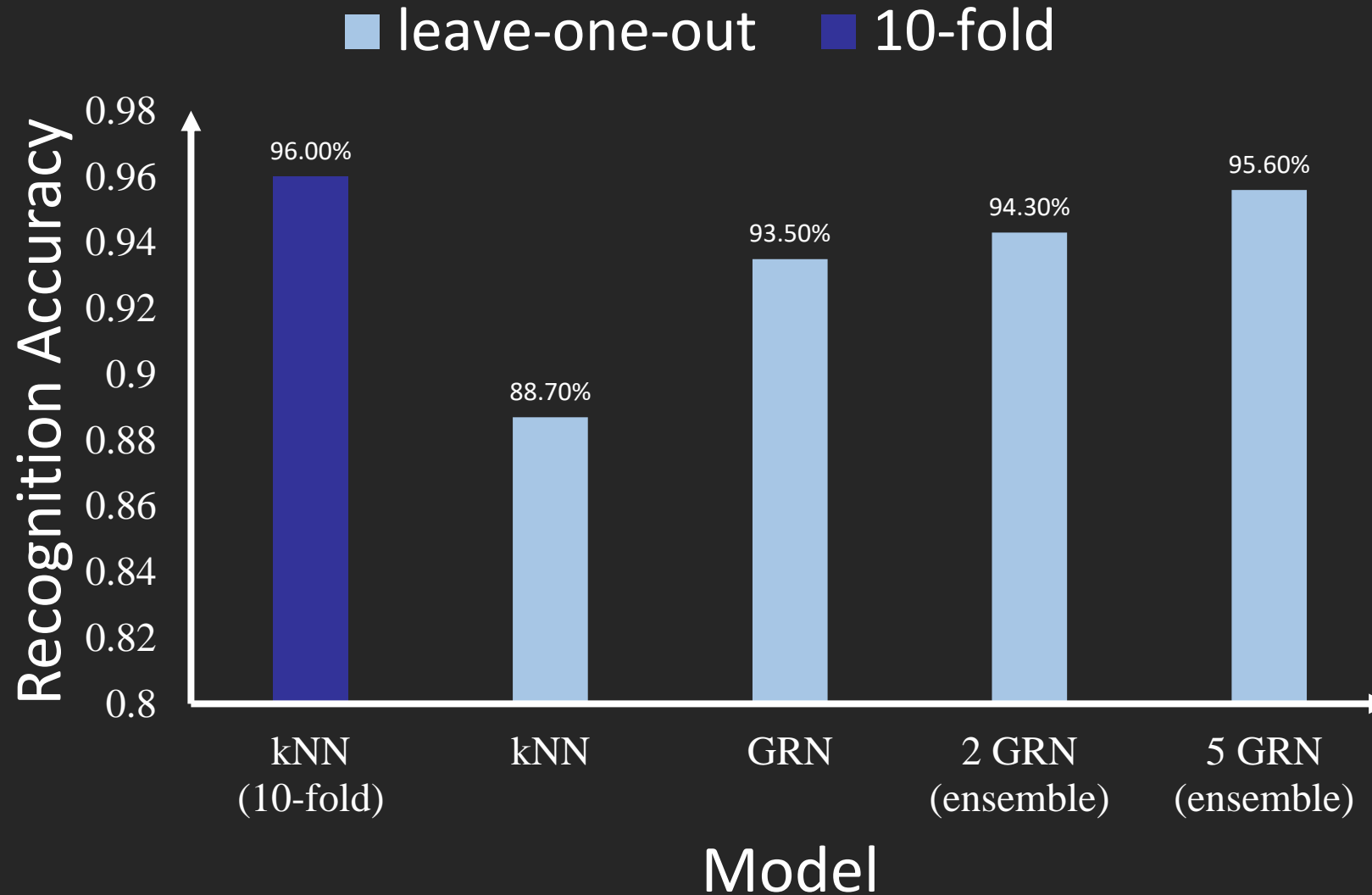
SMART is a generic model.



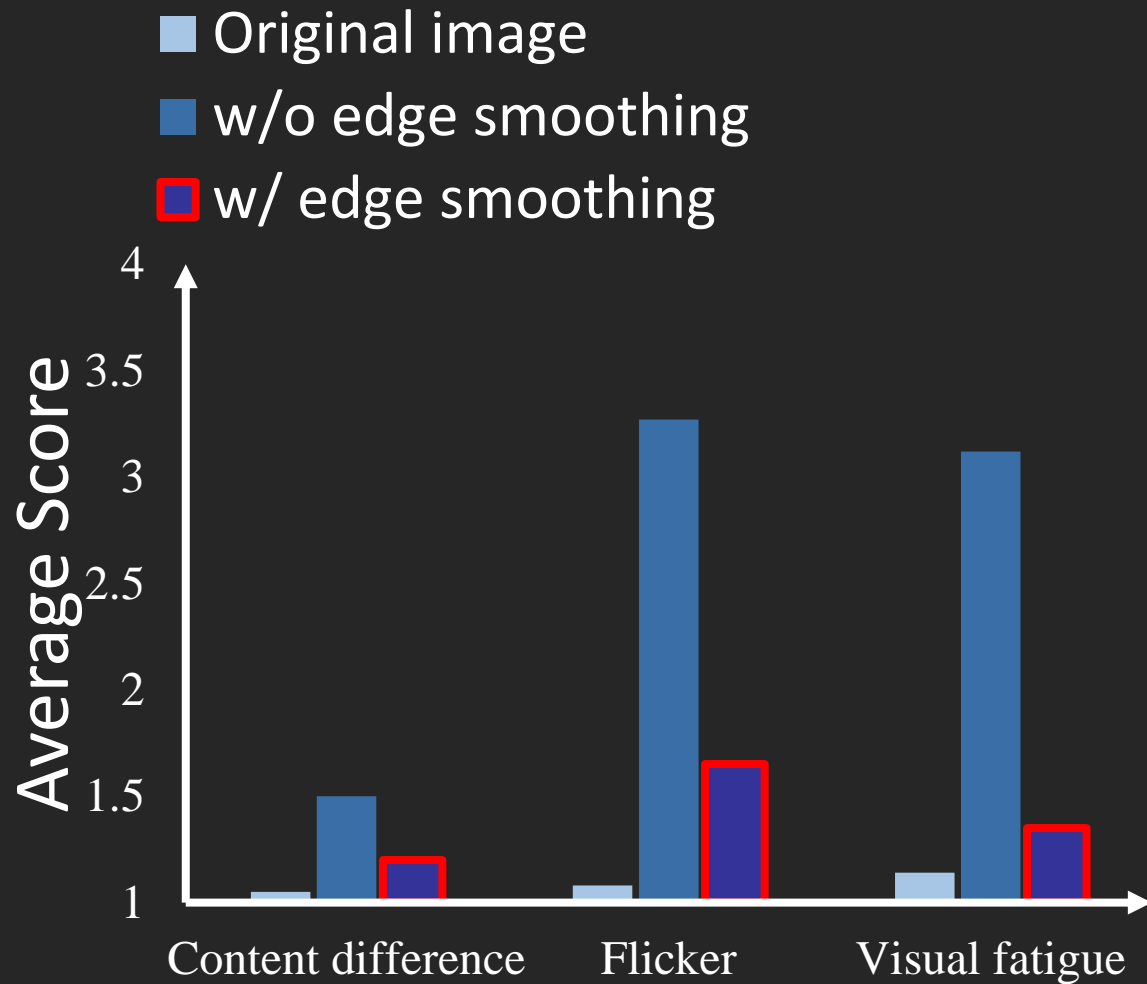
# Accuracy v.s. Different lighting environments



# Accuracy v.s. Unseen lighting environments



# User perception



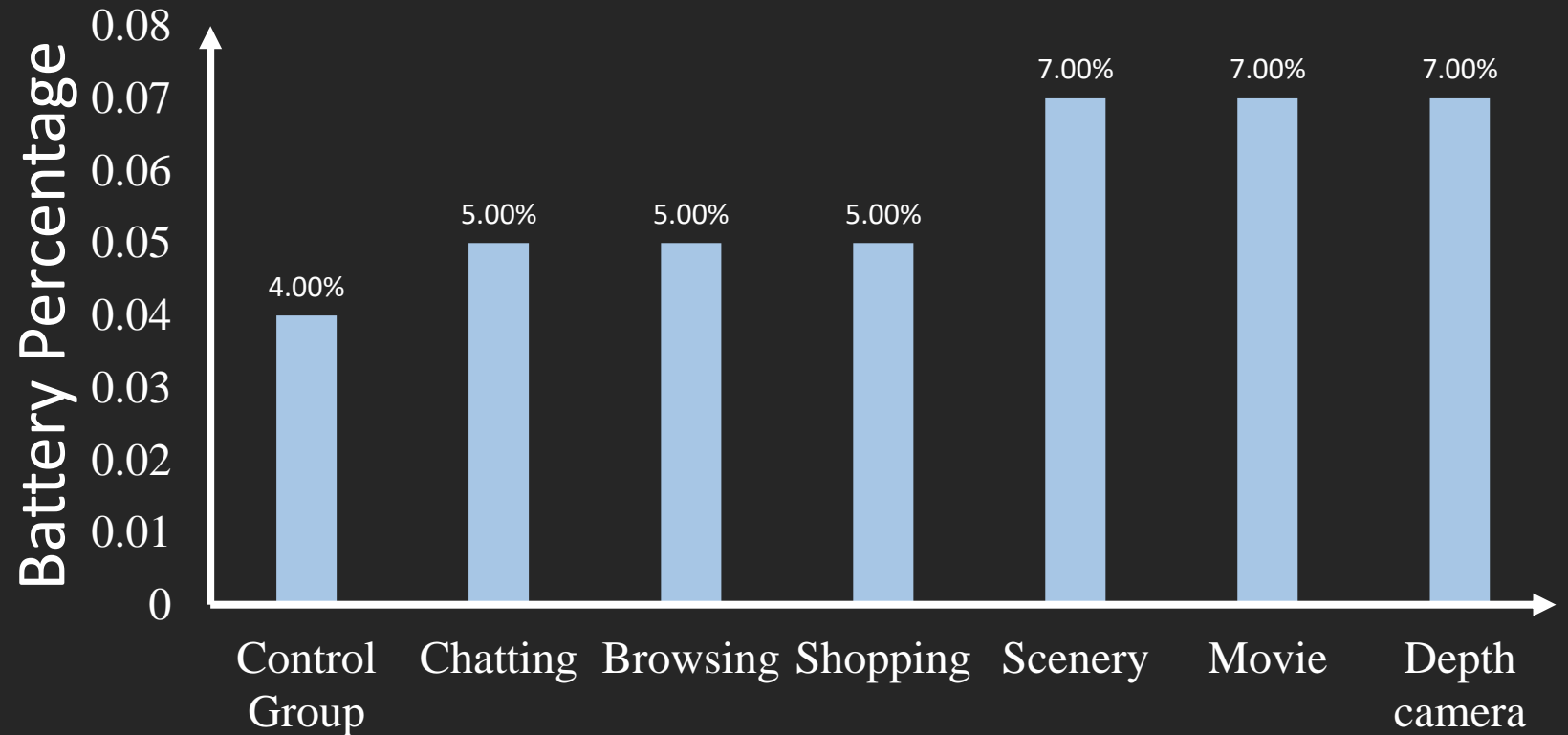
15 volunteers, 6 different images

Score	Content difference	Flicker	Visual fatigue
1	The same	No flickering	No fatigue
2	↓	↓	↓
3			
4			
	Evidently different	Evident flickering	Strong fatigue

# Power consumption comparison with depth camera



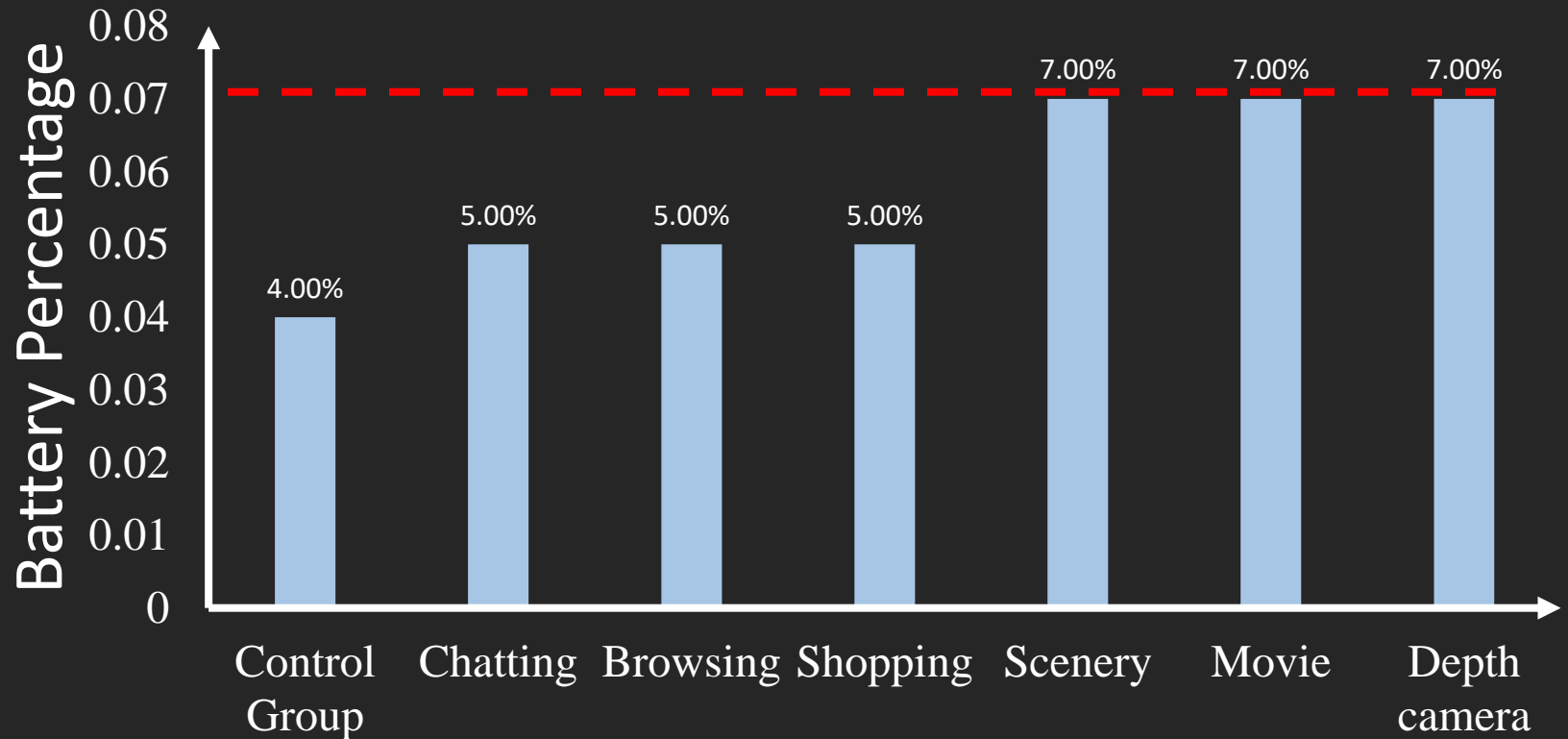
Huawei  
Mate30 Pro



# Power consumption comparison with depth camera



Huawei  
Mate30 Pro



SMART's power consumption is lower than depth-camera

Thanks for your attention!

Q&A