

SecurePilot: Improving Wireless Security of Single-Antenna IoT Devices

Huangxun Chen, Qianyi Huang¹, *Member, IEEE*, Chenyu Huang², Chenchen Liu, Tony Xiao Han, *Member, IEEE*, and Qian Zhang³, *Fellow, IEEE*

Abstract—With the arrival of the Internet of Things era, IoT devices and the services built on them make our lives more convenient and also raise public concerns on their vulnerability to attacks. Recent literature advocates physical-layer solutions to help IoT devices detect attacks instead of using sophisticated cryptographic methods. However, there is still no satisfying solutions for IoT devices with a single antenna and sparse traffic. Thus, we introduce SecurePilot to fill this gap. SecurePilot is an unsupervised and plug-and-play solution which works without an attacker’s knowledge in advance. It leverages the strengths of two orthogonal physical-layer information, propagation signatures and device signatures embedded in pilot signals to enable effective attack detection. It could work on single-antenna IoT devices with sparse traffic and also work compatibly with communication protocols. The experimental results show that SecurePilot can successfully detect 99.6% of attacks, triggering false alarms on 3.1% of legitimate traffic in a typical office environment.

Index Terms—Multipath channel, pilot signal, radio imperfection, single-antenna IoT, wireless security.

I. INTRODUCTION

RECENTLY, IoT devices have been widely deployed as one of the most important building blocks in smart homes, intelligent factories, and even smart cities to support numerous applications [1], [2]. In daily residential and office space, we have witnessed the increasing adoption of IoT devices, such as Amazon Ring doorbell [3], Google Nest thermostat [4], Philip smart bulbs [5], various smart locks [6], [7], smart speakers [8], [9], and health trackers [10], [11], which transmit many critical and private data using WiFi. Despite the convenience, IoT devices are particularly vulnerable to

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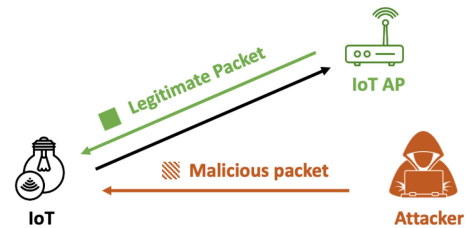
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Packet streams received by IoT:

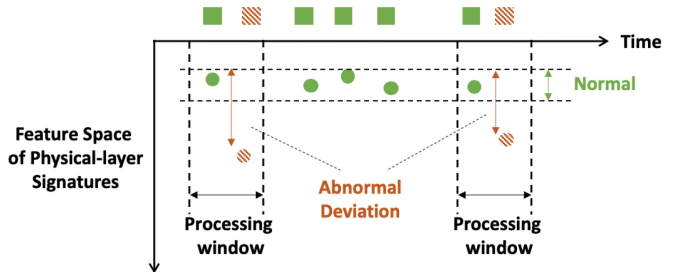


Fig. 1. Attack detection based on physical-layer signatures.

malicious attacks. As shown in Fig. 1, when an IoT device and an IoT access point (AP) interact with each other, an attacker may impersonate as a legitimate device to send packets to disturb their transmission, e.g., make them disassociated and launch a man-in-the-middle attack. Such attacks have been successfully launched to some commercial products, such as Amazon’s Ring Video Doorbell [12] and KeyWe Smart Lock [13]. In these real attacks, the attacker infers the key command of the transmission and injects it opportunistically to defraud the doorbell of home WiFi password or fool the smart lock to unlock the door. Thus, it presses for an effective and plug-and-play (i.e., not require any training phase or prior knowledge of attackers.) approach to find out the attack during transmission to help trigger further protective actions.

Many existing works [14]–[17] advocate using physical-layer propagation signatures to secure a wireless system against such attacks. An attacker is highly unlikely located at the exact same place as a legitimate device (IoT or IoT AP). Thus, when an attack occurs, an IoT receiver could observe a noticeable abnormal deviation in the feature space of physical-layer propagation signatures as shown in Fig. 1. It is worth mentioning that the feature space could be high-dimensional though Fig. 1 only presents a single dimension for convenient illustration. Compared with some advanced

cryptographic protocols, physical-layer solutions are generally more affordable for IoT devices with minimalist designs. However, we believe further efforts can be made to advance this direction. SecureArray [14] extracts sensitive Angle-of-Arrival (AoA) signatures using multiple half-wavelength separated antennas, which cannot work on IoT devices with a small form factor and a single antenna. SNAP [17] leverages the signal behavior in a transmitting antenna's near-field region to securely paring IoT devices, which cannot work when two devices are not in proximity. In addition, the frequency (i.e., number per second) of exchanged packets in many typical IoT networks, such as smart building and supply chain tracking, is below 5 Hz (i.e., sparse traffic) for power saving [18]. Thus, it may not be ideal for them to adopt channel state information (CSI) signatures that need to be averaged over multiple consecutive Wi-Fi packets (e.g., around 45 in [15]). We prefer physical-layer signatures whose effectiveness and robustness do not heavily rely on the number of available Wi-Fi packets. For the compatibility with communication (e.g., Wi-Fi), the backscatter-assisted solution [16] is not suitable since it requires transmitting sinusoidal waves. Many device identification schemes [19]–[24] generally register devices' signatures in the training stage for future classification/matching. However, detecting attacks in Fig. 1 prefers an unsupervised and plug-and-play solution which works without an attacker's knowledge in advance.

To fill this gap, this article introduces *SecurePilot* for IoT devices with single antennas and sparse traffic. The ultimate goal of our system is to help them find out attacks during transmission as in Fig. 1 without the need for multiple antennas, dense traffic, and the violation of WiFi transmission. *SecurePilot* leverages the physical-layer signatures embedded in pilot signals to achieve its goal. Specifically, partial subcarriers in each Wi-Fi symbol are populated with predefined modulated symbols, denoted as pilot signals in Fig. 3. Pilot-based signatures are compatible with WiFi transmission, and also more feasible for single-antenna IoT devices than AoA-based ones. Compared with CSI, they also carry propagation signatures and have advantages in the temporal domain to help relax the requirements of dense traffic, because given one WiFi packet with multiple symbols, we can only obtain one CSI sample but multiple samples of pilot signals.

Despite the above benefits, it is challenging to extract robust pilot-based signatures for attack detection due to the deficiency of pilot signals on the frequency domain. Pilot signals only capture propagation signatures of a few subcarriers rather than the whole channel (Fig. 3). To address this challenge, we observe that another dimension information, device-specific signatures incorporated in pilot signals can be leveraged to reinforce pilot-based signatures. Just as no two devices are located at the exact same location, no two ones have the exact same manufacturing imperfections. Through our derivation, a pair of symmetric pilot signals carries the effects of such imperfections. However, the limited pairs of pilot signals along the frequency domain make it still challenging to figure out effective signatures covering the superposition effect of both channel propagation and device imperfection. To overcome this challenge, we observe the cyclical varying symbol

patterns of the same pair of pilot signals along the time domain and leverage this property to extract both propagation and device-specific signatures simultaneously from pilot signals of the single packet for attack detection. The former is location- and time-specific, since the wireless channels are generally uncorrelated beyond the distance over a half-wavelength of carrier frequency and changing out of coherence time, while the latter is transceiver-specific, because even two radios of the same type can experience different manufacturing imperfections. Our method not only compensates deficiency of pilot signals in the frequency domain but also places more burden on attackers by making forging signatures more difficult.

Contributions: The contributions of this article are three-fold. First, we propose an effective scheme for IoT devices to detect attacks with single-antenna, sparse traffic, compatibility with original WiFi communication. Second, we provide an efficient method to extract robust pilot-based signatures, which combines the strengths of both channel propagation and device signatures embedded in pilot signals to make it harder to attack. Third, we evaluate our system under various compound factors. Our results show that the proposed system can detect 99.6% of attack attempts, while triggering false alarms on 3.1% of legitimate traffic in a typical office environment.

II. SYSTEM DESIGN

In this section, we first introduce the threat model addressed in this work (Section II-A). Next, we give an overview of the system workflow (Section II-B). Then, we illustrate the technical details on pilot signal extraction (Section II-C) and propagation and device signatures extraction from pilot signals of the single packet for comparison (Section II-D), which is the key step to detect attack during transmission. Finally, in Section II-E, we present an experiment to intuitively demonstrate the benefits of compound signatures in attack detection.

A. Threat Model

In our threat model, similar to previous works [14], [16], it is assumed that an attacker has some prior knowledge of the protocols and legitimate devices, such as SSID, MAC address, secret credentials, carrier frequency, coding scheme, etc. The attack may sniff traffic to get basic information of legitimate devices (e.g., device type) and further infer more from the Internet or the source like [25]. Thus, it can assemble packets following the well-known Wi-Fi protocol or copy one legitimate device's identity but include fake command/data to fool the other. It is assumed that attackers will not blindly launch attacks, because that will dramatically increase its exposure risk and also not efficient since IoT devices may not listen packets at most time (i.e., sleep mode) to save energy. It is assumed that the attacker takes a smarter move to first act as a sniffer to get the window of opportunity, once a wake-up IoT/IoT AP sends initial packet(s) to invite another device for link establishment and communication, the attacker grasps this opportunity to send its malicious packet. If the attack succeeds, it may cause unauthorized access to the IoT AP or rejection of the legitimate IoT during link establishment, or makes IoT's

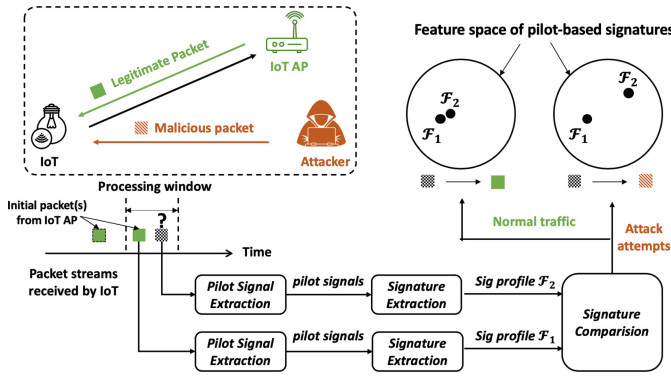


Fig. 2. System workflow of SecurePilot.

data delivered wrongly or stolen by the attacker during data sharing. It is assumed that IoT devices are equipped with a single antenna and they do not have prior knowledge of the attackers.

B. System Workflow and Overview

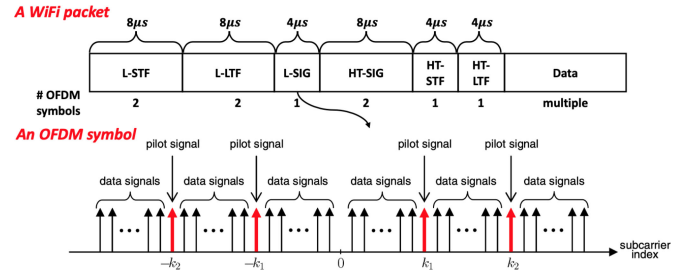
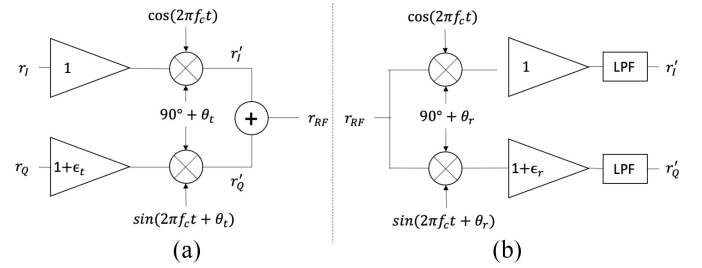
The workflow of SecurePilot is demonstrated in Fig. 2. The receiver will maintain a sliding processing window and initiate pilot-based signature extraction and comparison between two packets within the window. Based on the threat model in Section II-A, IoT initially receives one or a few legitimate packets. If the system detects the difference between two signature profiles to be within normal range, then IoT continues the normal transmission. Otherwise, if the system detects abnormal deviation between two profiles, then a potential attack is detected and proper actions should be executed like further examining or packet dropping. Next, we will introduce the detailed operations in the modules of pilot signal extraction, signature extraction, and comparison, respectively.

C. Pilot Signal Extraction

The first processing module of the system is to extract pilot signals from a WiFi packet. The Wi-Fi physical layer [26] builds upon the orthogonal frequency-division multiplexing (OFDM) technique, where a wide bandwidth (e.g., 20 MHz) is divided into multiple (e.g., 64) orthogonal subcarriers, each of which supports a constellation symbol with many bits per symbol. Given modulated symbols S_k ($k = -32, \dots, -1, 0, 1, \dots, 31$) transmitted on subcarriers and a 20-MHz sampling rate, a baseband OFDM waveform in Wi-Fi is constructed as an inverse Fourier transform of S_k

$$r(t) = \frac{1}{N} \sum_k S_k \exp(j2\pi k \Delta_F t), \quad 0 \leq t < T \quad (1)$$

where Δ_F ($=312.5$ kHz) is the subcarrier frequency spacing; T ($=3.2$ μ s) is the inverse Fourier transform symbol period with $\Delta_F = 1/T$, and N ($=64$) is the number of samples in the inverse Fourier transform. Among 64 subcarriers in WiFi (802.11n), besides data subcarriers and nonpopulated subcarriers, four subcarriers are used as pilot signals for phase and frequency tracking and training [27]. Numbering the subcarrier locations as $-32, -31, \dots, -1, 0, 1, \dots, 31$, the

Fig. 3. Frame structure of a WiFi packet and pilot signals in a WiFi OFDM symbol ($k_1 = 7$ and $k_2 = 21$).Fig. 4. Direct-conversion radio: I/Q imbalances in (a) transmission and (b) reception.

pilot subcarriers are located in $-21, -7, 7$, and 21 subcarriers (Fig. 3). Pilot signals are inserted in all symbols of L-SIG, H-SIG, and Data fields in Fig. 3, which means one WiFi packet has multiple samples of pilot signals.

Therefore, the module of pilot signal extraction reuses partial functions of packet reception, including downconversion, low-pass filter (LPF), analog-to-digital conversion (A/D), and FFT operation. Unlike the normal reception which conducts equalization to decode data signals afterward, we extract unequalized pilot signals and feeds them into the next module.

D. Pilot-Based Signatures Extraction and Comparison

As in Fig. 2, effective and robust signatures are critical to attack detection. Thus, this section will cover the technical details on extracting pilot-based signatures from a WiFi packet.

1) *Signatures Embedded in Pilot Signals*: Pilot-based signatures extracted by our method carry the superposition effects of both manufacture imperfections and channel propagation.

In terms of manufacture imperfections, most Wi-Fi network interface cards (NICs) adopt direct conversion radio architecture [28] as shown in Fig. 4, where quadrature/complex mixers are used to upconvert the signal to radio frequency (RF) for transmission, and downconvert it to baseband for the reception. It provides benefits for current consumption, size, radio performance, and inherently allows a great degree of channel bandwidth flexibility, but also suffers from inevitable I/Q imbalance [29], one type of manufacture imperfections.

In an ideal radio, I and Q branches have the same gain with $(\pi/2)$ phase difference. However, quadrature mixers in direct conversion radios are impaired by gain mismatch (ϵ) and phase mismatch (θ) of I and Q branches. To simplify the following analysis, this article adopts an I/Q imbalance model

where the effects of both gain and phase imbalances are on the Q branch. As shown in Fig. 4, the ideal signal $r(t) = r_I(t) + jr_Q(t)$, $r_I(t)$ and $r_Q(t)$ denote the real and imaginary parts of the ideal baseband signals without I/Q imbalance, respectively

$$\begin{aligned} r_I(t) &= r_{\text{RF}}(t) \cdot \cos(2\pi f_c t) \\ r_Q(t) &= r_{\text{RF}}(t) \cdot \sin(2\pi f_c t) \end{aligned} \quad (2)$$

where f_c is the carrier frequency. Then, the signal impaired by I/Q imbalance is $r'(t) = r'_I(t) + jr'_Q(t)$, where

$$\begin{aligned} r'_I(t) &= r_{\text{RF}}(t) \cdot \cos(2\pi f_c t) \\ &= r_I(t) \\ r'_Q(t) &= r_{\text{RF}}(t) \cdot (1 + \epsilon) \cdot \sin(2\pi f_c t + \theta) \\ &= (1 + \epsilon) \cos(\theta) \cdot r_Q(t) + (1 + \epsilon) \sin(\theta) \cdot r_I(t). \end{aligned} \quad (3)$$

From the perspective of communication, I/Q imbalances will cause channel estimation errors and disturb demodulation. Considerable works have estimated and compensated them to improve communication [30], [31]. From the perspective of security, I/Q imbalances are a kind of unique manufacturing imperfection, which are varied across different radios even those of the same type. Such device signatures may fluctuate due to temperature and device aging. However, this does not affect their effectiveness on attack detection in Fig. 2, because our system detects attacks by observing signature deviation within the processing window, i.e., it does not compare signatures of recent packets with a stored template long before.

To show the effect of this imperfection on pilot signals, we rearrange (3) as follows:

$$\begin{aligned} r'(t) &= r'_I(t) + jr'_Q(t) \\ &= r_I(t) + j[(1 + \epsilon) \cos(\theta) \cdot r_Q(t) + (1 + \epsilon) \sin(\theta) \cdot r_I(t)] \\ &= \alpha(r_I(t) + jr_Q(t)) + \beta(r_I(t) - jr_Q(t)) \\ &= \alpha r(t) + \beta r^*(t) \end{aligned} \quad (4)$$

where

$$\begin{aligned} \alpha &= \frac{1}{2} [1 + (1 + \epsilon)(\cos(\theta) - j \sin(\theta))] \\ \beta &= \frac{1}{2} [1 - (1 + \epsilon)(\cos(\theta) + j \sin(\theta))]. \end{aligned} \quad (5)$$

It is noticed that I/Q imbalance (ϵ and θ) generates an extra image signal $r^*(t)$, which is the complex conjugate of the original signal $r(t)$. Considering an OFDM-modulated WiFi baseband signal $r(t)$

$$\begin{aligned} r'(n) &= \alpha r(n) + \beta r^*(n) \\ &= \frac{\alpha}{N} \sum_{k=-N/2}^{k=N/2-1} S_k e^{j2\pi kn/N} + \frac{\beta}{N} \sum_{k=-N/2}^{k=N/2-1} S_k^* e^{-j2\pi kn/N}. \end{aligned} \quad (6)$$

By taking the N -point discrete Fourier transform (DFT) of the above equation, the signal in the frequency domain is

$$R'(k, n) = \alpha S(k, n) + \beta S^*(-k, n) \quad (7)$$

where $R'(k, n)$ and $S(k, n)$ denote the distorted symbol and original one at the k th subcarrier of the n th OFDM symbol, and α and β denote the device signatures stemming from radio's I/Q imbalance (gain and phase imbalances ϵ and θ).

From (7), it is noted that I/Q imbalance in WiFi causes the crosstalk phenomenon between symmetrical subcarriers, where symbol on subcarrier k leaks into mirror subcarrier $-k$ and *vice versa*. Since pilot signals are located in symmetrical subcarriers (see Fig. 3), we can extract device-specific signatures from mirror pilot signals.

Given a pair of transceivers, the transmitted signals will be distorted by transmitter's I/Q imbalance (α_t, β_t), wireless channel H , and receiver's I/Q imbalance (α_r, β_r) successively. Based on (7), the signal transmitted by the I/Q imbalanced transmitter is

$$X(k, n) = \alpha_t S(k, n) + \beta_t S^*(-k, n). \quad (8)$$

Then, given channel response at the k th subcarrier H_k

$$\begin{aligned} Y(k, n) &= H_k X(k, n) \\ &= H_k [\alpha_t S(k, n) + \beta_t S^*(-k, n)]. \end{aligned} \quad (9)$$

Finally, the received signal at I/Q imbalanced receiver is

$$R'(k, n) = \alpha_r Y(k, n) + \beta_r Y^*(-k, n). \quad (10)$$

Substituting (9) into (10), we have

$$R'(k, n) = C_1^k \cdot S(k, n) + C_2^k \cdot S^*(-k, n) \quad (11)$$

where

$$\begin{aligned} C_1^k &= \alpha_r H_k \alpha_t + \beta_r H_{-k}^* \beta_t^* \\ C_2^k &= \alpha_r H_k \beta_t + \beta_r H_{-k}^* \alpha_t^*. \end{aligned} \quad (12)$$

As shown in (5), α and β are functions of I/Q imbalance parameters, gain and phase imbalance ϵ and θ , which represent device-specific signatures. And channel response H represents the propagation signatures. Thus, (12) shows (C_1^k, C_2^k) which contain the effects from both device and propagation signatures. It is worth mentioning that the transmitter's device signatures (α_t, β_t) matter more than the receiver's ones (α_r, β_r) in attack detection in Fig. 2.

2) *Signature Extraction and Comparison*: If we can obtain two independent equations with the form as (11), compound physical-layer signatures (C_1^k, C_2^k) can be solved out and utilized in attack detection. An intuitive thought is to leverage two pairs of pilot signals along the frequency domain (see Fig. 3), the estimated channel responses H from CSI and the premeasured I/Q imbalances of the receiver (α_r, β_r) to solve the following equation set:

$$\begin{cases} R'(k_{p1}, n) = C_1^{k_{p1}} \cdot S(k_{p1}, n) + C_2^{k_{p1}} \cdot S^*(-k_{p1}, n) \\ R'(k_{p2}, n) = C_1^{k_{p2}} \cdot S(k_{p2}, n) + C_2^{k_{p2}} \cdot S^*(-k_{p2}, n) \end{cases} \quad (13)$$

where $k_{p1} \in \{7, -7\}$ and $k_{p2} \in \{21, -21\}$.

However, this method has fundamental flaws because I/Q imbalance parameters are frequency dependent [32]. Compared with pilot subcarriers in DVB-T only having 4-kHz

TABLE I
PILOT SIGNALS ACROSS WiFi OFDM SYMBOLS

$S(k_p, n) \backslash n$	0	1	2	3	4	...
k_p						
-21	1	1	1	-1	1	...
-7	1	1	-1	1	1	...
7	1	-1	1	1	1	...
21	-1	1	1	1	-1	...

frequency spacing [33], the pilot subcarriers in the Wi-Fi protocol are separated with larger spacing (14×312.5 kHz = 4375 kHz). Thus, (12) should be revised as

$$\begin{aligned} C_1^k &= \alpha_r^k H_k \alpha_i^k + \beta_r^k H_{-k}^* (\beta_i^k)^* \\ C_2^k &= \alpha_r^k H_k \beta_i^k + \beta_r^k H_{-k}^* (\alpha_i^k)^* \end{aligned} \quad (14)$$

Therefore, it is infeasible to solve (13). Instead of using pilot pairs along the frequency domain, we resort to pilot pairs of contiguous WiFi OFDM symbols along the time domain. Specifically, the equation set used to figure out the compound signatures is as follows:

$$\begin{cases} R'(k_p, n) = C_1^{k_p} \cdot S(k_p, n) + C_2^{k_p} \cdot S^*(-k_p, n) \\ R'(k_p, n+1) = C_1^{k_p} \cdot S(k_p, n+1) + C_2^{k_p} \cdot S^*(-k_p, n+1) \end{cases} \quad (15)$$

where $k_p \in \{7, -7, 21, -21\}$.

If we define a matrix A as follows:

$$A = \begin{bmatrix} S(k_p, n) & S^*(-k_p, n) \\ S(k_p, n+1) & S^*(-k_p, n+1) \end{bmatrix}. \quad (16)$$

A full-rank matrix A is the precondition of solving $(C_1^{k_p}, C_2^{k_p})$ from (15), i.e., $\text{rank}(A) = 2$. According to the WiFi standard [27], the modulated signals inserted at the positions of pilot signals for single-antenna devices are

$$S_n^{-21, -7, 7, 21} = \{\Psi_{n \oplus 4}, \Psi_{(n+1) \oplus 4}, \Psi_{(n+2) \oplus 4}, \Psi_{(n+3) \oplus 4}\} \quad (17)$$

where $n \oplus a$ indicates symbol number n modulo integer a , and the pattern Ψ_n is $\{\Psi_0 = 1, \Psi_1 = 1, \Psi_2 = 1, \Psi_3 = -1\}$. Thus, the pattern is cyclically shifted from symbol to symbol (Table I) due to the modulo indexing operation of $\Psi_{n \oplus 4}$. Thus, we can have a full-rank matrix A .

Based on (15), the module of signature extraction derives the compound signatures as follows:

$$\begin{bmatrix} C_1^{k_p} \\ C_2^{k_p} \end{bmatrix} = A^{-1} \begin{bmatrix} R'(k_p, n) \\ R'(k_p, n+1) \end{bmatrix} \quad (18)$$

where $k_p \in \{7, -7, 21, -21\}$. Then, the signature profiles are constructed as follows for comparison:

$$\mathcal{F} = \left\{ \left(\left| C_1^{k_p} \right|, \left| C_2^{k_p} \right| \right) \right\}, k_p \in \{7, -7, 21, -21\}. \quad (19)$$

Equation (15) requires pilot signals from at least two contiguous symbols to extract signatures. A Wi-Fi packet generally has several symbols depending on the amount of transmitted data and the modulation type. Thus, the compound signatures of a packet can be obtained by averaging multiple ones extracted from every two contiguous OFDM symbols that satisfy the full-rank requirement of matrix A .

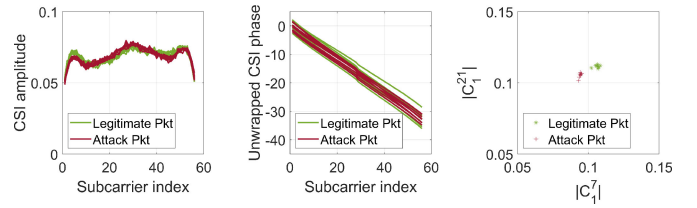


Fig. 5. From left to right: CSI amplitudes profiles, CSI phases profiles, and partial pilot-based signatures profiles of the received packets, respectively.

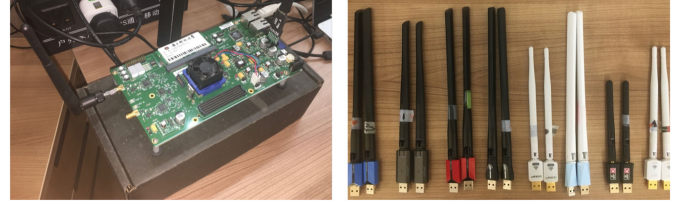


Fig. 6. Left: Radio front end of the prototype on Rice WARP 3.0. Right: Eight pairs of Wi-Fi radios operating in 2.4-GHz band act as the legitimate devices and active attackers.

In terms of signature comparison, to detect attack in plug-and-play manner, for two contiguous packets in the processing window, we extract pilot-based signatures, respectively, from them, i.e., we obtain two signature profiles \mathcal{F}_1 and \mathcal{F}_2 . Based on our evaluation, the differences between profiles of different transmitters are evident in the Euclidean space. Thus, we adopt the Euclidean distance to quantify their distinction as in (20). When the estimated distance $\mathcal{D}(\mathcal{F}_1, \mathcal{F}_2)$ is larger than a threshold η , a potential attack is detected; otherwise, they are regarded as normal traffic. The detailed discussion about threshold determination is elaborated in Section III-B1

$$\begin{aligned} \mathcal{D}(\mathcal{F}_1, \mathcal{F}_2) = \text{sqrt} \left(\sum_{k_p} \left\{ \left(\left| (C_1^{k_p})_{\mathcal{F}_1} \right| - \left| (C_1^{k_p})_{\mathcal{F}_2} \right| \right)^2 \right. \right. \\ \left. \left. + \left(\left| (C_2^{k_p})_{\mathcal{F}_1} \right| - \left| (C_2^{k_p})_{\mathcal{F}_2} \right| \right)^2 \right\} \right). \end{aligned} \quad (20)$$

E. Demonstrating Benefits of Compound Signatures

The key advantage of our system is combining two orthogonal dimensions of information from pilot signals of single packet, location- and time-specific propagation signatures and transceiver-specific ones to provide effective attack detection for IoT devices with single antenna and sparse traffic.

To demonstrate its benefits intuitively, we set up a stringent attack scenario. We run our system on a single-antenna receiver to collect packets from two other devices within wireless coherence time. One device acts as a legitimate user and the other acts as an attacker. Besides, their antennas are within 1-cm distance and they have the same type Wi-Fi radios. Within wireless coherence time, two devices take turns to send packets to the receiver. CSI amplitudes/phases of collected packets in Fig. 5 show that the propagation signatures of the attacker's packets are almost the same as those from the legitimate device. However, the extracted pilot-based signatures

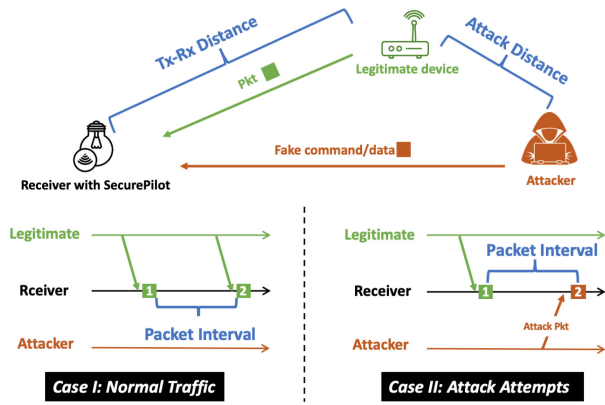


Fig. 7. Cases and compound factors in the evaluation.

in the rightmost of Fig. 5 still exhibit evident differences between two different transceivers with the assistance from transceiver-specific signatures.

III. EVALUATION

We first describe our experimental settings, then evaluate the system performance in different situations, respectively. Finally, we analyze the system latency.

A. Experimental Setting

The ultimate goal of our system is to help IoT detect attacks during transmission without the need of multiple antennas, dense traffic, and the violation of WiFi transmission. To achieve this goal, it is critical to detect whether two packets (expected to be sent by the same transmitter) within coherent time are sent from different transmitters or not. Therefore, our evaluation focuses on quantifying our system's performance on this key capability.

In the evaluation, we implement the proposed system (Fig. 6) on a laptop using MATLAB. A single-antenna radio front end implemented on the Rice WARP v3.0 platform [34] sends the received WiFi signals back to MATLAB for processing.

Eight pairs of Wi-Fi radios operating in the 2.4-GHz band are involved in experiments and each pair of them contains two Wi-Fi radios of the same type, i.e., they are manufactured by the same vendor and all their factory parameters, including antenna gain and sensitivity, are the same. It is worth mentioning that our goal is not to classify these 16 (eight pairs) devices. Instead, we use each pair of them to mimic stringent attack scenarios: an attacker uses the same type of radio as the legitimate device. For each pair, when one of them acts as the legitimate device, the other will act as the attacker. We adopt this setting to impose stringent attacks to challenge our system.

In the experiments, we let a pair of legitimate device and attacker send packets to the receiver equipped with our proposed system, covering the cases of both normal traffic and attack attempts in Fig. 7 with various compound factors (including different Tx–Rx distances, attack distances, packet intervals, packet durations, and radio types). The receiver runs the proposed system to detect attack attempts.

For static experiments (i.e., the devices did not move), we deploy the legitimate devices at 20 randomly chosen positions

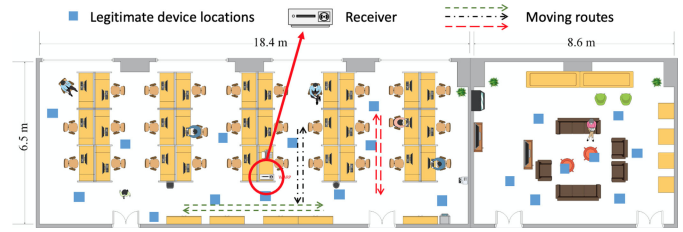


Fig. 8. Floor plan of our evaluation environment.

in a 27×6.5 m typical office environment as shown in Fig. 8. The tested positions (blue squares in Fig. 8) include both the line-of-sight (LOS) and non-LOS (NLOS) cases, and also cover the positions behind or near the wood cabinet, plastic water dispenser, mental machine cases, leather sofa, concrete wall, and people who are typing in the office to make our evaluation more comprehensive and realistic.

In terms of location of attackers, it is well known that location correlation is one of the important properties of wireless propagation channels, i.e., the propagation characteristics are generally uncorrelated beyond the distance over a half-wavelength of the carrier frequency [35]. Thus, to test the system robustness, we randomly deploy attackers at a specific distance with respect to (w.r.t.) legitimate devices, which vary from 2.5 m down to around 5 cm. It is worth mentioning that the “attack distance” is different from the “Tx–Rx distance.” As blue squares are shown in Fig. 8, the distance between Tx and Rx is up to 15.5 m in NLOS cases. Attack distance refers to the distance between the legitimate device and the attacker (see Fig. 7), which varies from 5 cm to 2 m in our evaluation. Besides, the intervals fall in the range from 2 ms to 2 s for every two consecutive Wi-Fi packets for signature extraction and comparison.

We conduct the evaluation in a functioning office and run the experiments in both daytime and nighttime. Besides the deployed devices, the wireless environment of our evaluation site has three other APs and tens of clients communicating.

For dynamic experiments, we evaluate two cases, one of them has a volunteer walking and doing activities nearby deliberately, and the other has both the legitimate device and the attacker moving at the same time. Other settings are similar to those in static experiments.

We adopt the following metrics to evaluate the performance.

- 1) *True Positive (TP)*: An attack attempt is identified correctly (detected attack).
- 2) *False Negative (FN)*: An attack attempt is identified as normal traffic (missed attack).
- 3) *False Positive (FP)*: A normal traffic is identified as attack attempt (false alarm).
- 4) *True Negative (TN)*: A normal traffic is identified correctly (normal traffic).
- 5) *Attack Detection Rate* = $\frac{TP}{TP+FN}$: The ratio of detected attacks among all attacks.
- 6) *Attack Miss Rate* = $\frac{FN}{TP+FN}$: The ratio of missed attacks among all attacks.
- 7) *False Alarm Rate* = $\frac{FP}{FP+TN}$: The ratio of false alarm among all normal traffic.
- 8) *Legitimate Detection Rate* = $\frac{TN}{FP+TN}$: The ratio of detected normal traffic among all normal traffic.

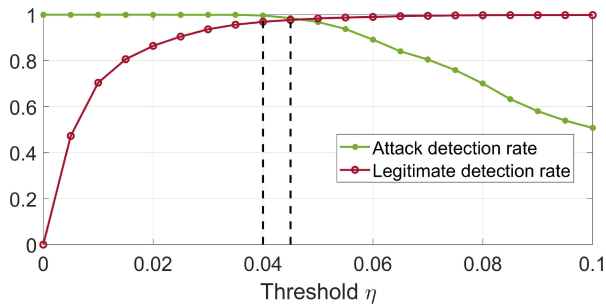


Fig. 9. System performance w.r.t. various threshold η .

B. Experiments in Relatively Static Environment

In this section, we present the system performance in a typical office environment when devices are static. We evaluate the system with different combinations of Wi-Fi radio types, device locations, distances between attackers and legitimate devices, and time intervals between collected Wi-Fi packets.

1) *Overall Performance and Threshold Determination:* The distance \mathcal{D} between signature profiles (Fig. 2) should be compared with an appropriate threshold η to reject attack attempts and accept normal traffic. To determine the best threshold, we examine the attack detection rate and legitimate detection rate for various choices of threshold η . The results averaging across different radio types, Tx–Rx distances, attack distances, and packet intervals are shown in Fig. 9. It is obvious that the attack detection rate increases when the threshold η decreases, while the legitimate detection rate has the opposite trend. That is because when threshold η decreases, the bound to be identified as normal traffic tightens. Thus, more attack attempts are excluded, resulting in a high attack detection rate. However, when threshold η becomes smaller, some legitimate traffic may also be misrecognized as attacks, resulting in a low legitimate detection rate. When $\eta = 0.045$, SecurePilot achieves 97.6% attack detection rate and 97.2% legitimate detection rate, i.e., triggering false alarm on 2.8% of legitimate traffic. We argue that such system has less tolerance to attack detection than false alarm. Thus, we choose to trade a little false alarm for a higher attack detection rate by setting a stricter threshold $\eta = 0.04$, where SecurePilot achieves 99.6% attack detection rate at a false alarm rate as 3.1%. We evaluate with threshold $\eta = 0.04$ in the remainder of our evaluation.

2) *Impact of Distance Between Attacker and Legitimate Device:* Usually, the attacker will be far away from the legitimate device to reduce exposure risk. However, it is still possible that the attacker can be closer when smart devices become smaller and even miniature. Thus, to demonstrate the system capability on handling the cases where the attackers are close to legitimate users, we evaluate the performance w.r.t. different attack distances between them. In particular, we move an attacker from around 2.5 m to 5 cm away from a legitimate user to evaluate the system performance. The results are shown in Fig. 10, which are averaged across different radio types, Tx–Rx distances, and packet intervals. It is noticed that we achieve almost 100% attack detection rate under different attack distances, even for closer ones, 5 cm, and 10 cm, which validates the system effectiveness in attack detection for IoT

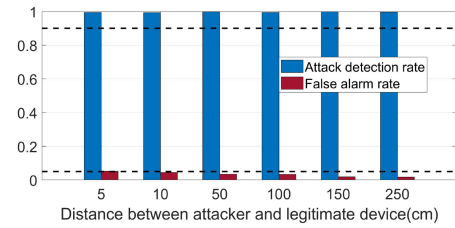


Fig. 10. Different attack distances.

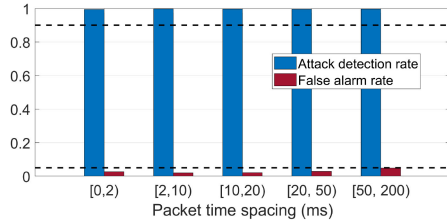


Fig. 11. Different packet intervals.

devices. However, when the attack distances become smaller, the false alarm rates also become higher since the distinction on propagation signatures, a part of pilot-based signatures, becomes smaller. However, they are still lower than 5% false alarm rate, which is acceptable for most IoT devices.

3) *Impact of Interpacket Time:* The channel is dynamic between any particular antenna pair in both amplitude and phase. Our pilot-based signatures incorporate the propagation signatures, so that the channel stability has effects on the signature stability. Therefore, we present the performance results for different packet intervals, averaging across multiple radio types, Tx–Rx distances, and attack distances.

Fig. 11 shows that in a typical working office environment when the devices are static, with the packet intervals from 2 ms to 2 s, SecurePilot still achieves good performance on attack detection, but obviously with an increased false alarm rate. The reason that attack detection rates are not affected by the large packet intervals is that the signatures of malicious packets do not change to be similar to the legitimate ones as time goes. However, with packet interval increases, the legitimate ones will have larger signature distances due to channel instability so that some will be misregarded as attack attempts, resulting in a higher false alarm rate.

4) *Impact of Packet Duration (Number of WiFi OFDM Symbols):* As mentioned before, the final signatures of a packet as in (19) can be obtained by averaging multiple ones extracted from every two consecutive WiFi OFDM symbols, since a packet generally includes several symbols. Considering some IoT devices may only send a small amount of data at a time, i.e., a small number of symbols in a packet, we naturally ask that does the number of OFDM symbols in a packet have effects on the system performance. Therefore, we evaluate the system performance w.r.t. the number of OFDM symbols. As shown in Fig. 12, the increase of symbol number can help reduce false alarm rate a bit, because averaging may rule out more noises and provide more stable signatures. But even with two symbols, the false alarm rate is within 5%, which is acceptable for most daily IoT devices. Thus, even

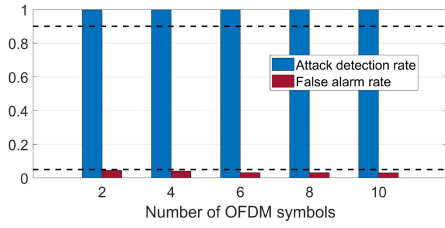


Fig. 12. Different symbol numbers.

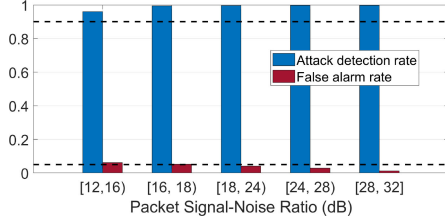


Fig. 13. Different SNR levels.

the packet carries little data, our system can utilize pilots from two consecutive OFDM symbols in L-SIG and H-SIG fields (Fig. 3) to extract signatures for attack detection.

5) *Impact of Packet Signal-to-Noise Ratio*: Considering in real scenarios, some IoT devices may experience a low signal-to-noise ratio (SNR) due to long distance away transmitter or obstacles. We naturally wonder whether the proposed system still has a good performance on the noise-corrupted received signals. Therefore, our data collection covers both the short/long-range and LOS/NLOS cases. We evaluate the system performance w.r.t. the SNR of collected packets. We calculate the SNR of a packet based on estimated error vector magnitude (EVM) between received symbols and constellation symbols [36]. As shown in Fig. 13, the increase of the SNR level can help reduce false alarm rate and improve the attack detection rate, because a high SNR level helps to extract more stable signatures. But even in low-SNR cases, the attack detection rate is above 95% and the false alarm rate is only a little bit above 5%.

C. Experiments in Dynamic Environment

Coherence time is another important property of wireless propagation channels. Wireless coherence time (T_c) refers to the time duration over which the wireless channel can be considered unchanging with high likelihood. It is determined by the carrier wavelength λ (m) and maximum object velocity v (m/s) in the environment as $T_c = [(9\lambda)/(16\pi v)]$ [14]. Given a normal walking speed 1.5 m/s and 2.4-GHz band, $T_c = 14.3$ ms. Thus, in this section, we set up two dynamic environments to evaluate the system performance.

1) *People Waking Around*: In the first case, we deliberately ask a volunteer to walk and do some activities (i.e., playing on smartphones and waving hands) along the routes as shown in Fig. 8, which cover the cases, including walking close around the devices, approaching the receiver, and going across the channel between transceivers. We evaluate the system performance w.r.t. different packet intervals. As shown in Fig. 14, compared with the results in static experiments, when there are substantial movements nearby, the wireless

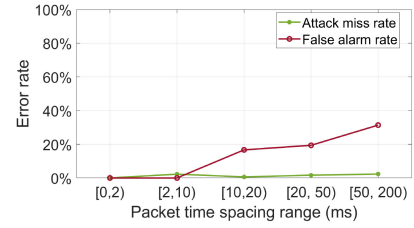


Fig. 14. People walking around.

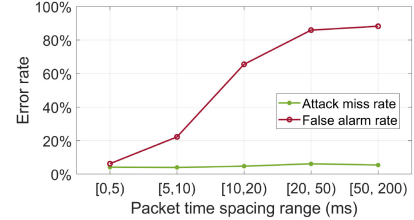


Fig. 15. Moving devices.

coherent time becomes much shorter. Thus, to achieve both the low attack miss rate and the false alarm rate, the packet interval is better to be within 10 ms. Similar to Fig. 11, the false alarm rate is rising with the increasing packet interval. In the experiments of Fig. 11, people in the office are sitting and typing, i.e., tiny movements. While in this part, the volunteer performs substantial movements on purpose around the devices during data collection. Thus, false alarm rates in Fig. 14 increase more sharply compared with those in Fig. 11.

2) *Moving Devices*: In the second case, we evaluate a more challenging case where both attacker and legitimate device are moving at the same time. We place both devices on a platform with wheels and keep their antennas separated by 50 cm. We ask a volunteer to push/pull them along the routes shown in Fig. 8. These routes cover both LOS and NLOS cases since the working stations and people will block the direct transmission paths for some portions of routes. We evaluate the system performance w.r.t. different packet intervals. The results are shown in Fig. 15. Compared with Fig. 14, the wireless coherence time becomes much shorter, i.e., 5 ms for moving devices. The possible reason is that walking people around may pose effects on only one or two propagation paths, but a moving device experiences dramatical changes of each propagation path, which pushes the allowed packet interval down to 5 ms.

To sum up, in the dynamic environment, the wireless coherence time becomes shorter as expected in theory. Therefore, the allowed packet interval becomes shorter accordingly. However, considering short packets (microsecond-level duration) and low duty cycle of IoT devices, a millisecond-level packet interval is sufficient for most scenarios.

D. System Latency

A real-time system may prefer low-latency schemes. In our current implementation, the components of latency are analyzed as follows.

- 1) T_1 denotes time for packet detection and sample recording by receiver. When two symbols in L-SIG/H-SIG fields (Fig. 3) are utilized for pilot extraction, $T_1 = 24 \mu\text{s}$.

- 2) T_2 denotes the time for transferring samples to MATLAB. If we transmit time-domain samples of two symbols, there are 160 samples ($20 \text{ MHz} \times 4 \mu\text{s} \times 2$) transferred at the rate of 1 Mb/s supported by the WARP platform. Thus, $T_2 = (160 \text{ samples}) \times (32 \text{ bits/sample}) / (1 \text{ Mb/s}) = 5.12 \text{ ms}$. If the FFT operations are conducted to extract frequency-domain pilot signals on hardware level, then there are only eight samples ($4 \text{ pilot subcarriers} \times 2 \text{ symbols}$) to be transferred, and $T_2 = (8 \text{ samples}) \times (32 \text{ bits/sample}) / (1 \text{ Mb/s}) = 256 \mu\text{s}$
- 3) T_3 denotes the time for compute the signatures and make the comparison. For our current MATLAB implementation with an Intel Core i7, 2.0-GHz CPU, and 8-GB RAM, the processing time is around 2 ms.

Therefore, the total latency from the start of an examined packet is less than 8 ms, which will be improved when partial processing can be implemented on the hardware level to reduce transfer cost for samples.

IV. RELATED WORK

A. Physical-Layer Propagation Signatures

In recent years, physical-layer propagation signatures have been extensively exploited to secure wireless systems against attacks. CSITE [15] uses CSI measurements averaged in time over around 45 packets to form a signature. Its performance is relevant to the traffic intensity of the legitimate user, Patwari and Kasera [37] and Zhang *et al.* [38] measured channel impulse response as temporal propagation signatures to identify the link between a pair of legitimate transceivers. SecureArray [14] constructs the highly sensitive AoA signature to secure Wi-Fi against attacks, which relies on multiple half-wavelength separated antennas, which does not fit for IoT devices with a small form factor and a single antenna. ShieldScatter [16] resorts to nearby backscatters to help single-antenna devices extract multipath propagation signatures. But it transmits sinusoidal waves and controls the tags to reflect them, which is not compatible with existing WiFi transmission. Physical-layer propagation signatures also play a critical role in proximity detection. Many existing works [17], [39]–[42] use propagation signatures to securely pair two wireless devices in proximity (within half-wavelength of carrier frequency in general). However, they do not aim to protect the devices separated beyond a certain distance against attacks. In summary, the physical-layer propagation signatures are location-specific. If the attacker has chances to be located near the legitimate device (e.g., using miniature attack devices), it is difficult to distinguish them only relying on propagation signatures.

B. Physical-Layer Device Signatures

A large body of literature has explored the device signatures for device identification. PARADIS [43] extracts minute transmitter-specific imperfections that are acquired at manufacture from the wireless signals and apply machine-learning tools to achieve NIC identification with 99% accuracy. Jana and Kasera [19] and Kohno *et al.* [20] exploited small, microscopic deviations in device hardware, clock skews for

client fingerprinting. Hua *et al.* [21] derived the carrier frequency offsets (CFOs) of wireless devices from CSI of tens of consecutive Wi-Fi packets as their hardware fingerprints. Liu *et al.* [22] extracted the nonlinear phase errors of different subcarriers from CSI as device signatures for identification. Most works on device identification generally register devices' signatures in the training stage for future classification/matching [23], [24]. However, different from device identification, our work focuses on attack detection. Thus, we propose an unsupervised and plug-and-play solution with no need for prior knowledge of attackers, since we detect attacks by observing abnormal signature deviation within the processing window. In addition, it is beneficial to combine the strengths of orthogonal signatures, both location- and time-specific propagation ones and device-specific ones to place more burden on attackers.

V. DISCUSSION

A. Integrating With CSI

SecurePilot extracts signatures within one packet, where one CSI can also be extracted from the preamble (i.e., L-LTF/HT-LTF in Fig. 3). In theory, propagation signatures carried in the preamble can be included to enhance the system. However, we then need to balance the weight between signatures from preamble and pilot signals, which complicates the system unnecessarily given pilot-based signatures have achieved satisfying performance. It is also worth mentioning that we cannot extract compound signatures from preamble as those from pilot signals. Because unlike cyclically shifted pattern in pilots signals (Table I), the symbols in the preamble part are repeated (i.e., exactly the same) so that it fails to satisfy the full-rank requirement. Thus, the current design does not include CSI.

B. Forge the Legitimate Device's Compound Signature

There are a few possible schemes that the attacker may employ to crack the system.

- 1) The attacker has a chance to be located near to the legitimate device and has prior knowledge of the Wi-Fi radio type of the legitimate device. Our experimental results in Fig. 5 have demonstrated that our system can handle such attacks due to the help from unique devices signatures that vary across different Wi-Fi radios even of the same type.
- 2) The attacker obtains the legitimate device's compound signatures, and then uses an advanced radio platform to mimic the device's signature at a different location in order not to be discovered. We argue that this is difficult to be realized. The attacker first needs to be at the exact same position as the receiver to collect the legitimate device's signature. Besides, the radio difference between the attacker and the receiver also affects collected signatures since I/Q imbalances of the reception side also manifest themselves into signatures.

Even we assume this signature can somehow be obtained, it is still challenging for the attacker to mimic it. To mimic the part of the propagation signature, the attacker may exploit the method in [44] to emulate multipath propagations. To mimic

the part of device signatures, we need to assume the attacker is equipped with advanced software-defined radios (SDRs) so that it can independently manipulate each pilot signal to mimic the legitimate device's signature. However, it is still impractical because I/Q imbalances are inevitable in direct-conversion radios, even for advanced SDRs, such as WARP and USRP. Therefore, when the attacker tries to manipulate symbol S_k on the pilot subcarrier k to forge α^k and β^k , I/Q imbalances of its own radio will manifest this manipulation into the results of α^{-k} and β^{-k} . The need to craft pilot signals that match all signatures in (19) places quite a burden on the attacker. Moreover, in Wi-Fi protocols, signals on pilot subcarriers are generally used for phase and frequency tracking [27], i.e., helping demodulate data subcarriers. Thus, such manipulation may affect the data reception of the attack packet, i.e., the attacker may fail to deliver fake command/data.

In summary, our system places heavy burden on the attacker to forge the legitimate device's signatures.

C. Compatibility With Various Antenna Capability

In this work, we emphasize the single-antenna capability of the receiver side since attack detection is conducted by the receiver. However, our proposed system can be easily extended to apply on multiple-antenna IoT devices. As shown in Section II, our physical-layer signature is derived from pilot signals of a Wi-Fi packet received from an antenna. If there are multiple antennas, we can obtain signatures for each antenna and expand the signature profiles \mathcal{F} (19) accordingly for attack detection. The use of multiple antennas enhances signatures and will place more burden on the attackers to forge them. It is worth mentioning that our system does not have requirements on the transmitter side. In common practice, the antennas used for a link are negotiated and fixed between the transmitter and the receiver. Thus, the transmitter can use either a single antenna or multiple antennas. To sum up, our proposed system can work compatibly on cases of different antenna capabilities of both the transmitter and the receiver side.

D. System Overhead

Our system provides a plug-and-play method to detect attacks by mapping received packets to pilot-based signature space and observing abnormal signature deviation. Thus, it can be called by upper layer protocols to help find out attacks. In every call, it introduces little overhead in terms of both hardware and software by reusing partial functions of original packet reception and processing pilot signals with low latency. The upper layer protocol can flexibly balance the total overhead and security level by adjusting the calling frequency. For example, one of the most common threats to the link establishment process is malicious deauthentication frame [45]. In this case, the association protocol may choose to call our system to help verify the received deauthentication frames for security.

VI. CONCLUSION

This work provides a plug-and-play attack detection system for IoT devices without the need of multiple antennas, dense traffic, and the violation of WiFi transmission, and also with

no need of prior knowledge of attackers. The proposed system extracts two orthogonal physical-layer information from pilot signals of single packet, combining strengths of both propagation and device signatures to detect attacks effectively and make forging signatures more difficult for attackers. The experimental results show that our system can successfully detect 99.6% attack attempts, only triggering false alarms on 3.1% of legitimate traffic in a typical office environment.

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